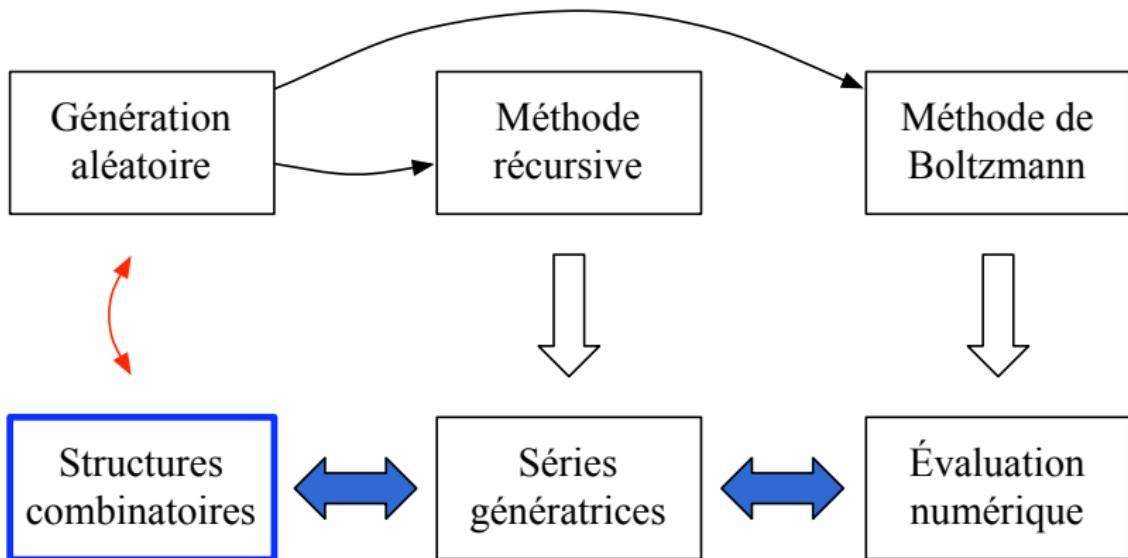


Itération de Newton combinatoire pour le calcul de l'oracle de Boltzmann

Carine Pivoteau

en collaboration avec Bruno Salvy et Michèle Soria

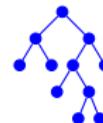
Motivations



Exemples de spécifications combinatoires

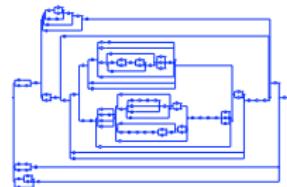
- des arbres binaires planaires :

$$\mathcal{B} = \mathcal{Z} + \mathcal{Z} \times \mathcal{B}^2$$



- des circuits série-parallèle :

$$\begin{aligned}\mathcal{S} &= \text{SEQ}_{\geq 2}(\mathcal{P} + \mathcal{Z}) \\ \mathcal{P} &= \text{MSET}_{\geq 2}(\mathcal{S} + \mathcal{Z})\end{aligned}$$



- un langage algébrique :

$$\mathcal{C}_0 = \mathcal{Z} \mathcal{C}_1 \mathcal{C}_2 \mathcal{C}_3 (\mathcal{C}_1 + \mathcal{C}_2)$$

$$\mathcal{C}_1 = \mathcal{Z} + \mathcal{Z} \text{SEQ}(\mathcal{C}_1^2 \mathcal{C}_3^2)$$

$$\mathcal{C}_2 = \mathcal{Z} + \mathcal{Z}^2 \text{SEQ}(\mathcal{Z} \mathcal{C}_2^2 \text{SEQ}(\mathcal{Z})) \text{SEQ}(\mathcal{C}_2)$$

$$\mathcal{C}_3 = \mathcal{Z} + \mathcal{Z}(3\mathcal{Z} + \mathcal{Z}^2 + \mathcal{Z}^2 \mathcal{C}_1 \mathcal{C}_3) \text{SEQ}(\mathcal{C}_1^2)$$

Exemples de spécifications combinatoires

- des arbres binaires planaires :

$$\mathcal{B} = \mathcal{Z} + \mathcal{Z} \times \mathcal{B}^2$$

- des circuits série-parallèle :

$$\begin{aligned}\mathcal{S} &= \text{SEQ}_{\geq 2}(\mathcal{P} + \mathcal{Z}) \\ \mathcal{P} &= \text{MSET}_{\geq 2}(\mathcal{S} + \mathcal{Z})\end{aligned}$$

- un langage algébrique :

$$C_0(z) = zC_1(z)C_2(z)C_3(z)(C_1(z) + C_2(z))$$

$$C_1(z) = z + z/(1 - C_1(z)^2C_3(z)^2)$$

$$C_2(z) = z + z^2/((1 - zC_2(z)^2/(1 - z))(1 - C_2(z)))$$

$$C_3(z) = z + z(3z + z^2 + z^2C_1(z)C_3(z))/(1 - C_1^2(z))$$

Exemples de spécifications combinatoires

- des arbres binaires planaires :

$$\mathcal{B} = \mathcal{Z} + \mathcal{Z} \times \mathcal{B}^2$$

- des circuits série-parallèle :

$$\mathcal{S} = \text{SEQ}_{\geq 2}(\mathcal{P} + \mathcal{Z})$$

$$\mathcal{P} = \text{MSET}_{\geq 2}(\mathcal{S} + \mathcal{Z})$$

- un langage algébrique : pour $z = 0.1$

$$C_0 = C_0(0.1) = 0.1C_1C_2C_3(C_1 + C_2)$$

$$C_1 = C_1(0.1) = 0.1 + 0.1/(1 - C_1^2C_3^2)$$

$$C_2 = C_2(0.1) = 0.1 + 0.01/((1 - C_2^2/9)(1 - C_2))$$

$$C_3 = C_3(0.1) = 0.1 + 0.1(0.31 + 0.01C_1C_3)/(1 - C_1^2)$$

```

sys := [
  C0 = x C1 C2 C3 (C1 + C3), Z = x, C1 = x
  +
  
$$\frac{x}{1 - C1^2 C3^2}, C2 = 2 x + \frac{x}{(1 - x C1^2 C2^2) (1 - C2)},$$

  C3 = x + 
$$\frac{x (3 x + x^2 + x^2 C1 C3)}{1 - C1^2}$$

]

```

```

>
> [seq(subs(t,c0),t=solve(subs(x=0.1,sys)))];;
[0.0003125169973, 0.0007429960174, 0.01391132169,
 -0.01391089776, 0.06534819752, 0.1516695772,
 0.5931967039, -0.5909308297, -0.002843524044,
 -0.006587551424, -0.02496904471, 0.02486320262,
 1.016379119, 0.2631789750 + 0.1384080116 I,
 -0.3391146531, 0.2631789750 - 0.1384080116 I,
 -0.002894993353, -0.006718005666, -0.02619777844,
 0.02609673139, -0.07632515320, -0.1768253273,
 -0.6704728314, 0.6676342030, 1.015911152, 0.2617092228
 + 0.1379131433 I, -0.3359391708, 0.2617092228
 - 0.1379131433 I]

```

```

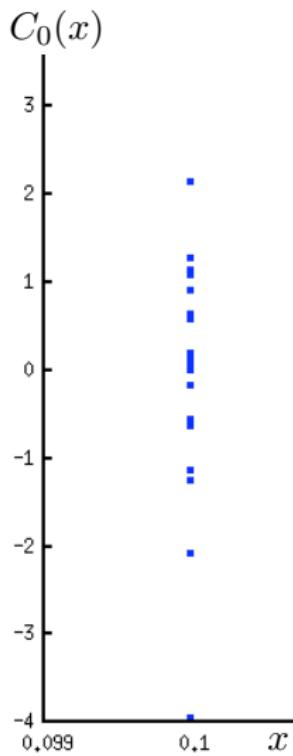
sys := [
C0 = x C1 C2 C3 (C1 + C3), Z = x, C1 = x
+  $\frac{x}{1 - C1^2 C3^2}$ , C2 = 2 x +  $\frac{x}{(1 - x C1^2 C2^2) (1 - C2)}$ ,
C3 = x +  $\frac{x (3 x + x^2 + x^2 C1 C3)}{1 - C1^2}$ 
]

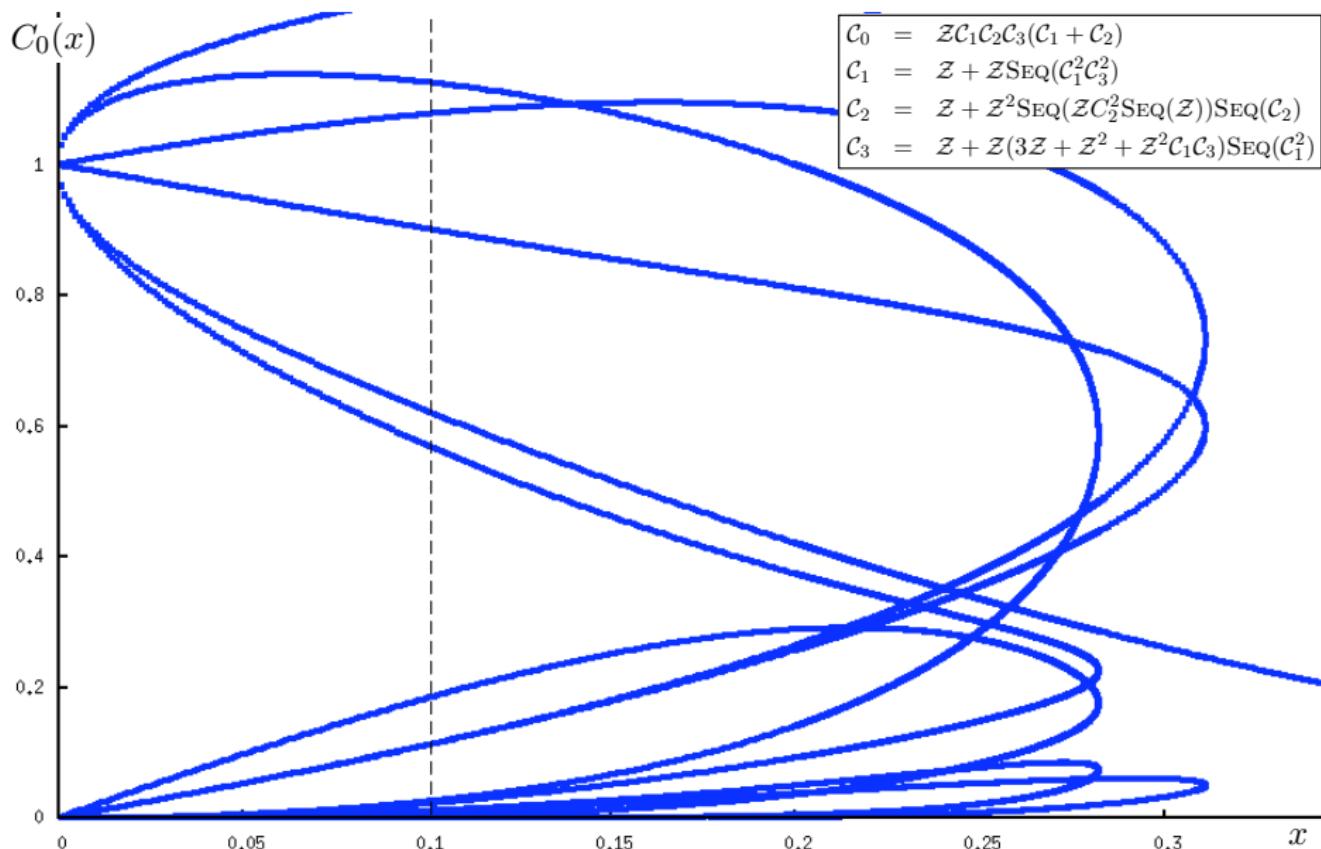
```

```

>
> [seq(subs(t,c0),t=solve(subs(x=0.1,sys)))];;
[0.0003125169973, 0.0007429960174, 0.01391132169,
-0.01391089776, 0.06534819752, 0.1516695772,
0.5931967039, -0.5909308297, -0.002843524044,
-0.006587551424, -0.02496904471, 0.02486320262,
1.016379119, 0.2631789750 + 0.1384080116 I,
-0.3391146531, 0.2631789750 - 0.1384080116 I,
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0.02609673139, -0.07632515320, -0.1768253273,
-0.6704728314, 0.6676342030, 1.015911152, 0.2617092228
+ 0.1379131433 I, -0.3359391708, 0.2617092228
- 0.1379131433 I]

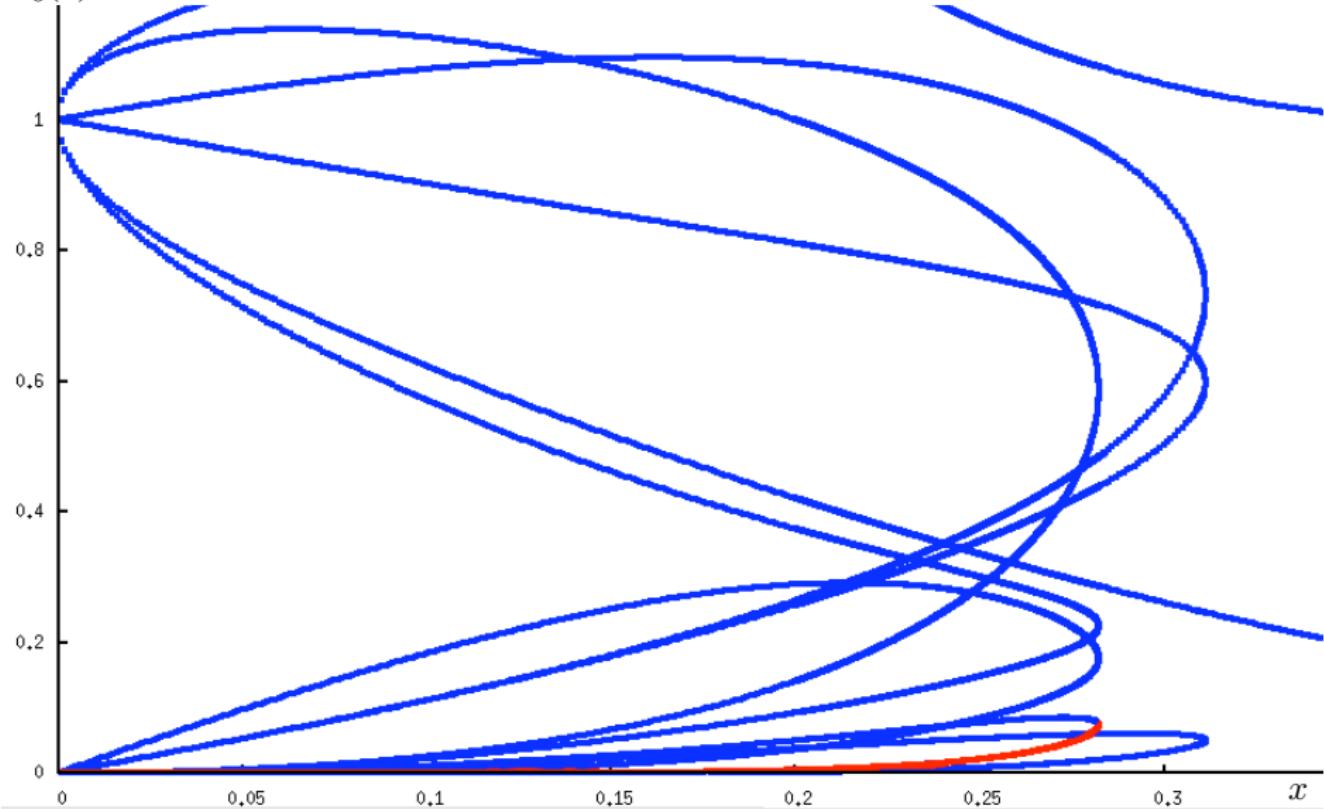
```



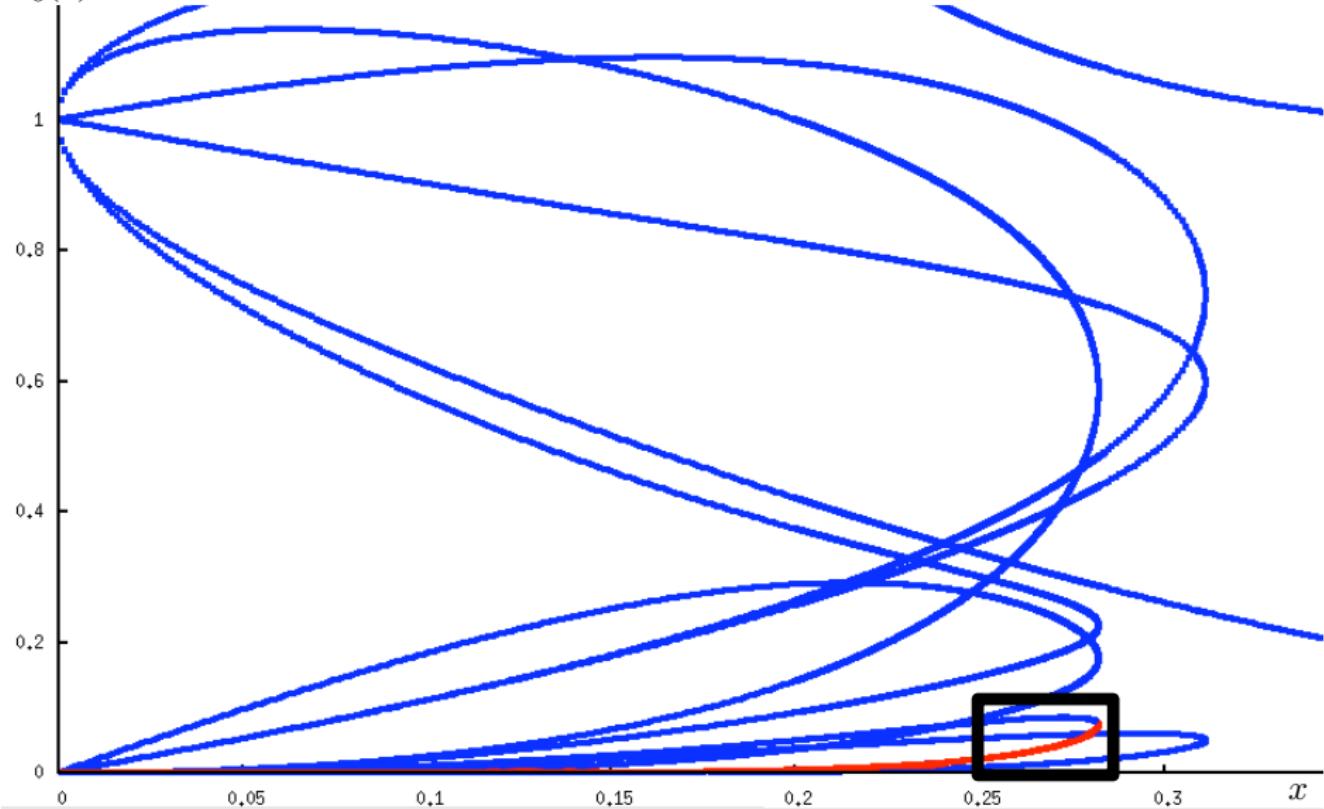


\mathcal{C}_0	$=$	$\mathcal{Z}\mathcal{C}_1\mathcal{C}_2\mathcal{C}_3(\mathcal{C}_1 + \mathcal{C}_2)$
\mathcal{C}_1	$=$	$\mathcal{Z} + \mathcal{Z}\text{SEQ}(\mathcal{C}_1^2\mathcal{C}_3^2)$
\mathcal{C}_2	$=$	$\mathcal{Z} + \mathcal{Z}^2\text{SEQ}(\mathcal{Z}\mathcal{C}_2^2\text{SEQ}(\mathcal{Z}))\text{SEQ}(\mathcal{C}_2)$
\mathcal{C}_3	$=$	$\mathcal{Z} + \mathcal{Z}(3\mathcal{Z} + \mathcal{Z}^2 + \mathcal{Z}^2\mathcal{C}_1\mathcal{C}_3)\text{SEQ}(\mathcal{C}_1^2)$

$$C_0(z) = 18z^5 + 90z^6 + 222z^7 + 1032z^8 + 4446z^9 + 23184z^{10} + 126492z^{11} + 732264z^{12} + \dots$$



$$C_0(z) = 18z^5 + 90z^6 + 222z^7 + 1032z^8 + 4446z^9 + 23184z^{10} + 126492z^{11} + 732264z^{12} + \dots$$



Proposition

L'itération de Newton converge (rapidement) vers la solution.

Approche

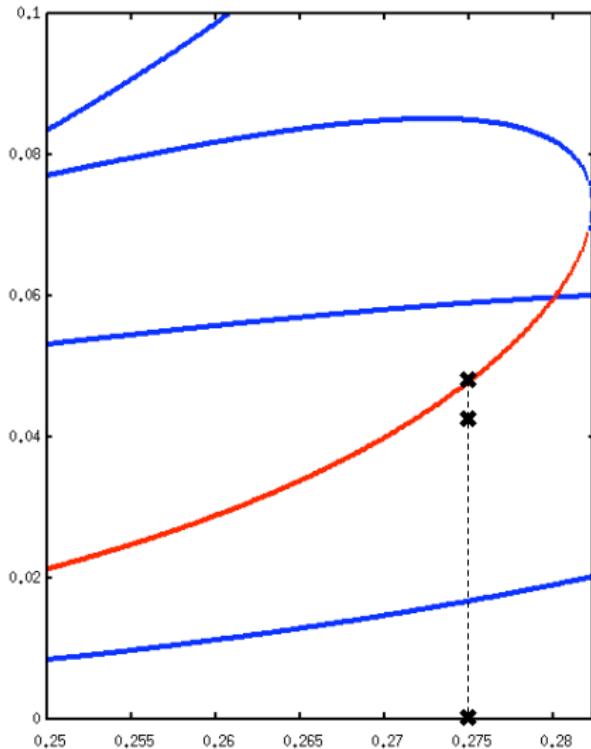
convergence de
l'itération **numérique**



évaluation des séries
de **dénombrement**



système d'équations
combinatoires



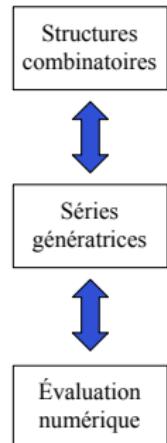
Résultat

Théorème (2008)

Pour tout système combinatoire $\mathbf{Y} = \mathbf{H}(\mathcal{Z}, \mathbf{Y})$ bien fondé, l'itération de Newton :

- converge *quadratiquement* vers l'espèce solution,
- calcule les suites d'énumération en complexité *quasi optimale* par rapport au nombre de coefficients,
- fournit un oracle numérique dont la convergence est asymptotiquement *quadratique*.

★ bonus : itération de Newton optimisée.



Calculer la solution par itération

Cadre combinatoire

Théorème (Espèces implicites, Joyal 81)

Le système combinatoire

$$\begin{aligned} Y_1 &= H_1(Z, Y_1, Y_2, \dots, Y_m) \\ Y_2 &= H_2(Z, Y_1, Y_2, \dots, Y_m) \\ &\vdots && \vdots \\ Y_m &= H_m(Z, Y_1, Y_2, \dots, Y_m) \end{aligned}$$

admet une *unique solution* dès que :

- la matrice jacobienne $\frac{\partial H}{\partial \mathbf{Y}}(0, \mathbf{0})$ est *nilpotente*
- $H(0, \mathbf{0}) = 0$.

Exemple : les arbres binaires

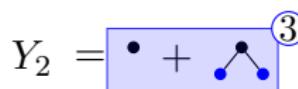
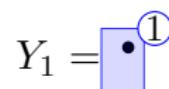
$$Y = \mathcal{Z} + \mathcal{Z} \times Y^2$$

$$Y = H(\mathcal{Z}, Y)$$

$$Y_{k+1} = \mathcal{Z} + \mathcal{Z} \times Y_k^2$$

$$\text{Itération : } Y_{k+1} = H(\mathcal{Z}, Y_k)$$

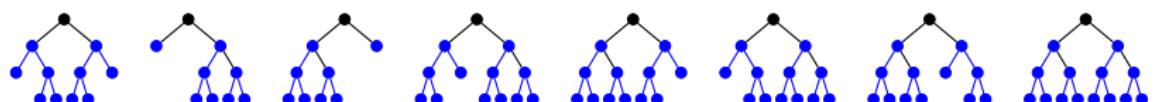
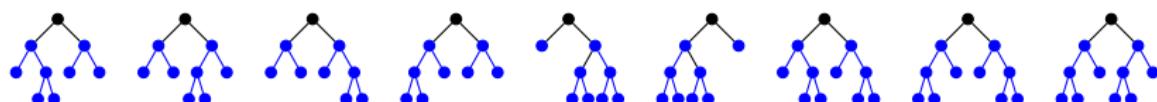
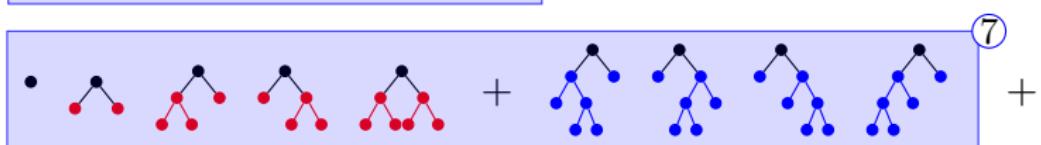
$$Y_0 = 0$$



$$Y_3 =$$



$$Y_4 =$$



Séries génératrices

$$Y(z) = z + z\widehat{Y}^2(z)$$

$$\widehat{Y}(z) = H(z, \widehat{Y}(z))$$

$$\widehat{Y}_{k+1}(z) = z + z\widehat{Y}_k(z)^2$$

$$\text{Itération : } \widehat{Y}_{k+1}(z) = H(z, \widehat{Y}_k(z))$$

$$\widehat{Y}_0(z) = \mathbf{0}$$

$$\widehat{Y}_1(z) = z$$

$$\widehat{Y}_2(z) = z + z^3$$

$$\widehat{Y}_3(z) = z + z^3 + 2z^5 + z^7$$

$$\widehat{Y}_4(z) = z + z^3 + 2z^5 + 5z^7 + 6z^9 + 6z^{11} + 4z^{13} + z^{15}$$

$$\widehat{Y}_5(z) = z + z^3 + 2z^5 + 5z^7 + 14z^9 + 26z^{11} + 44z^{13} + 69z^{15}$$

$$\widehat{Y}(z) = z + z^3 + 2z^5 + 5z^7 + 14z^9 + 42z^{11} + 132z^{13} + 429z^{15} + \dots$$

convergence pour les structures \Rightarrow convergence pour les séries

Itération numérique

$$Y(x) = x + xY^2(x)$$

$$Y(x) = H(x, Y(x))$$

$$Y_{k+1} = 0.2 + 0.2Y_k^2$$

$$\text{Itération : } Y_{k+1}(x) = H(x, Y_k(x))$$

$$Y_0 = \hat{Y}_0(0.2) = \mathbf{0}$$

$$Y_1 = \hat{Y}_1(0.2) = \mathbf{0.2}$$

$$Y_2 = \hat{Y}_2(0.2) = \mathbf{0.208}$$

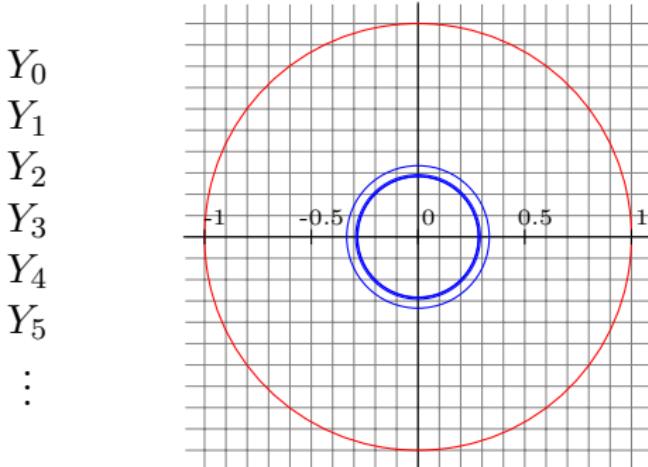
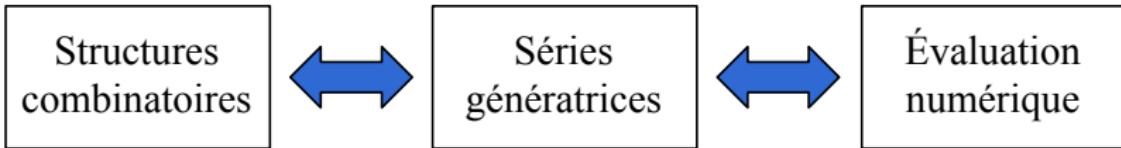
$$Y_3 = \hat{Y}_3(0.2) = \mathbf{0.2086528}$$

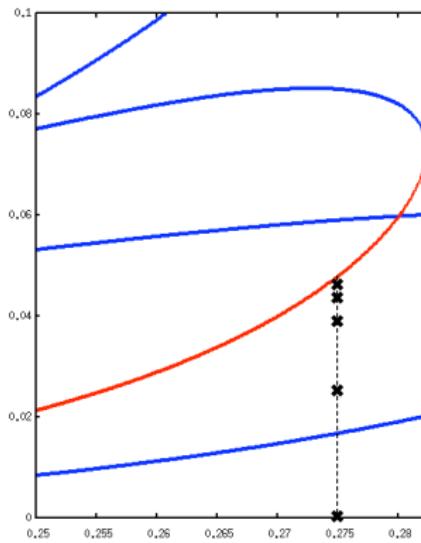
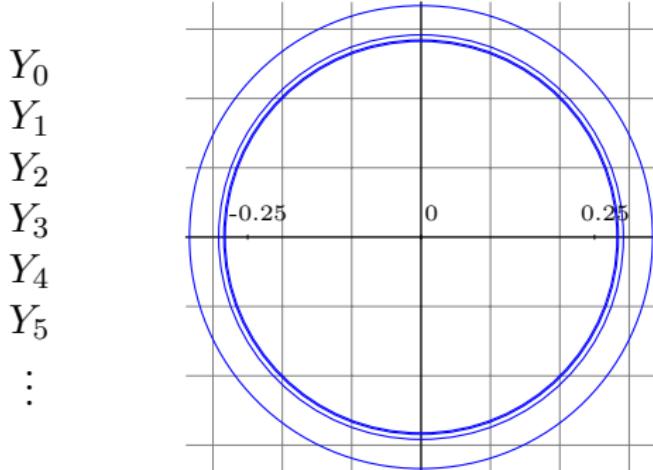
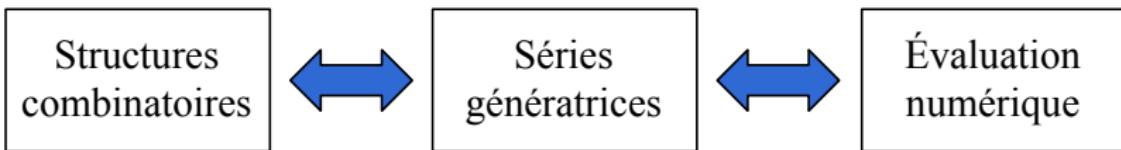
$$Y_4 = \hat{Y}_4(0.2) = \mathbf{0.208707198189568\dots}$$

$$Y_5 = \hat{Y}_5(0.2) = \mathbf{0.2087117389152279\dots}$$

$$Y = \hat{Y}(0.2) = \mathbf{0.2087121525220799\dots}$$

- pour toute valeur de $x < \rho$
- itération numérique \Leftrightarrow évaluer la série solution en x .





Itération de Newton

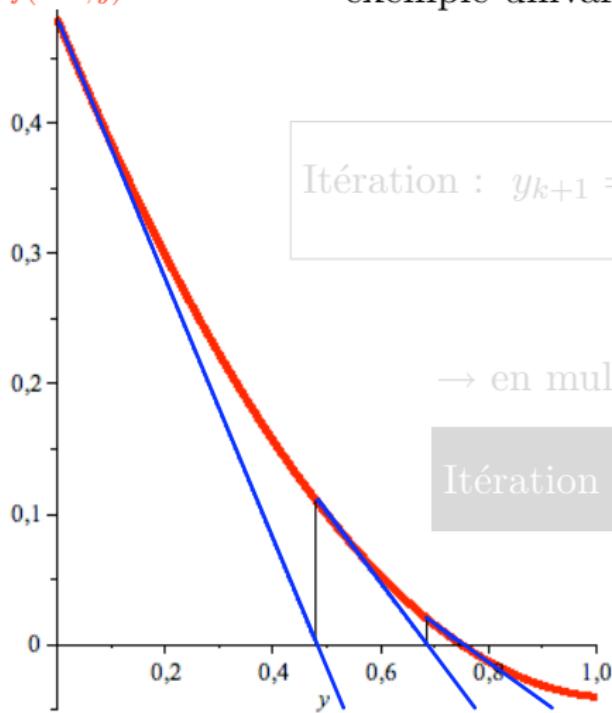
Principe de l'itération de Newton

$f(0.48, y)$

← exemple univarié :

$$y(x) = x + xy^2(x)$$

$$f(x, y) = x + xy^2 - y$$



$$\text{Itération : } y_{k+1} = y_k - \frac{f(x, y_k)}{\frac{\partial f}{\partial y}(x, y_k)}$$

→ en multivarié :

$$\text{Itération : } y_{k+1} = y_k - \left(\frac{\partial f}{\partial y}(x, y_k) \right)^{-1} f(x, y_k)$$

Principe de l'itération de Newton

$f(0.48, y)$

← exemple univarié :

$$y(x) = x + xy^2(x)$$

$$f(x, y) = x + xy^2 - y$$

0,4

0,3

0,2

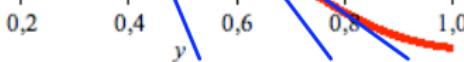
0,1

0

$$\boxed{\text{Itération : } y_{k+1} = y_k - \frac{f(x, y_k)}{\frac{\partial f}{\partial y}(x, y_k)}}$$

→ en multivarié :

$$\boxed{\text{Itération : } y_{k+1} = y_k - \left(\frac{\partial f}{\partial y}(x, y_k) \right)^{-1} f(x, y_k)}$$



Principe de l'itération de Newton

 $f(0.48, y)$

← exemple univarié :

$$y(x) = x + xy^2(x)$$

$$f(x, y) = x + xy^2 - y$$

0,4
0,3
0,2
0,1
0

Itération : $y_{k+1} = y_k - \frac{f(x, y_k)}{\frac{\partial f}{\partial y}(x, y_k)}$

→ en multivarié :

$$\text{Itération : } y_{k+1} = y_k - \left(\frac{\partial f}{\partial y}(x, y_k) \right)^{-1} f(x, y_k)$$

0,2 0,4 0,6 0,8 1,0
 y

Convergence numérique

$$Y(x) = x + xY^2(x)$$

$$Y(x) = H(x, Y(x))$$

$$\text{Itération : } Y_{k+1} = Y_k + (I - \frac{\partial H}{\partial Y}(x, Y_k))^{-1}(H(x, Y_k) - Y_k)$$

$$\text{pour } x = 0.48, \quad Y_{k+1} = Y_k + \frac{1}{1-0.96Y_k}(0.48 + 0.48Y_k^2 - Y_k)$$

$$Y_0 = \mathbf{0}$$

$$Y_1 = \mathbf{0.48}$$

$$Y_2 = \mathbf{0.68510385756676557863501483679525\dots}$$

$$Y_3 = \mathbf{0.74409429531735785069315411659589\dots}$$

$$Y_4 = \mathbf{0.74994139686483588184679391778624\dots}$$

$$Y_5 = \mathbf{0.74999999411376420459420080511077\dots}$$

$$Y_6 = \mathbf{0.74999999999999994060382090306852\dots}$$

$$Y_7 = \mathbf{0.749999999999999999999999999999999999997\dots}$$

convergence asymptotiquement quadratique

Newton sur les séries

$$\widehat{Y} = z + z\widehat{Y}^2(z)$$

$$\widehat{Y}(z) = H(z, \widehat{Y})$$

$$\text{Itération : } \widehat{Y}_{k+1} = \widehat{Y}_k + (I - \frac{\partial H}{\partial \widehat{Y}}(z, \widehat{Y}_k))^{-1}(H(z, \widehat{Y}_k) - \widehat{Y}_k)$$

$$\widehat{Y}_{k+1} = \widehat{Y}_k + \frac{1}{1-2z\widehat{Y}_k}(z + z\widehat{Y}_k^2 - \widehat{Y}_k)$$

$$\widehat{Y}_0 = \mathbf{0}$$

$$\widehat{Y}_1 = \mathbf{z}$$

$$\widehat{Y}_2 = \mathbf{z} + \mathbf{z}^3 + \mathbf{2z}^5 + 4z^7 + 8z^9 + 16z^{11} + 32z^{13} + 64z^{15} + \dots$$

$$\widehat{Y}_3 = \mathbf{z} + \mathbf{z}^3 + \mathbf{2z}^5 + \mathbf{5z}^7 + \mathbf{14z}^9 + \mathbf{42z}^{11} + \mathbf{132z}^{13} + 428z^{15} + \dots$$

$$\widehat{Y}_4 = \mathbf{z} + \mathbf{z}^3 + \mathbf{2z}^5 + \mathbf{5z}^7 + \dots + \mathbf{2674440z}^{29} + 9694844z^{31} + \dots$$

Dérivée combinatoire et matrice jacobienne

$$H(\mathcal{Z}, Y) = \bullet + \begin{array}{c} \bullet \\ \diagdown \quad \diagup \\ Y \quad Y \end{array}$$

$$\frac{\partial H}{\partial Y}(\mathcal{Z}, Y) = \begin{array}{c} \bullet \\ \diagup \quad \diagdown \\ Y \end{array} + \begin{array}{c} \bullet \\ \diagdown \quad \diagup \\ Y \end{array}$$

$$H(\mathcal{Z}, Y) = (H_1(\mathcal{Z}, Y), H_2(\mathcal{Z}, Y)) = (\bullet + \begin{array}{c} \bullet \\ \diagdown \quad \diagup \\ Y_1 \quad Y_2 \end{array}, \begin{array}{c} \bullet \\ \diagup \quad \diagdown \\ Y_2 \quad Y_1 \quad Y_1 \quad Y_1 \quad Y_2 \end{array})$$

$$\frac{\partial H}{\partial Y} = \begin{pmatrix} \frac{\partial H_1}{\partial Y_1} & \frac{\partial H_1}{\partial Y_2} \\ \frac{\partial H_2}{\partial Y_1} & \frac{\partial H_2}{\partial Y_2} \end{pmatrix} = \begin{pmatrix} \begin{array}{c} \bullet \\ \diagdown \quad \diagup \\ Y_1 \quad Y_1 \end{array} & \begin{array}{c} \bullet \\ \diagup \quad \diagdown \\ Y_2 \quad Y_1 \end{array} \\ \begin{array}{c} \bullet \\ \diagup \quad \diagdown \quad \diagup \quad \diagdown \\ Y_2 \quad Y_1 \quad Y_1 \quad Y_2 \end{array} & \begin{array}{c} \bullet \\ \diagup \quad \diagdown \quad \diagup \quad \diagdown \\ Y_2 \quad Y_1 \quad Y_1 \quad Y_2 \end{array} \end{pmatrix}$$

Dérivée combinatoire et matrice jacobienne

$$H(\mathcal{Z}, Y) = \bullet + \begin{array}{c} \bullet \\ \diagdown \quad \diagup \\ Y \quad Y \end{array}$$

$$\frac{\partial H}{\partial Y}(\mathcal{Z}, Y) = \begin{array}{c} \bullet \\ \diagup \quad \diagdown \\ Y \end{array} + \begin{array}{c} \bullet \\ \diagdown \quad \diagup \\ Y \end{array}$$

$$H(\mathcal{Z}, Y) = (H_1(\mathcal{Z}, Y), H_2(\mathcal{Z}, Y)) = (\bullet + \begin{array}{c} \bullet \\ \diagdown \quad \diagup \\ Y_1 \quad Y_2 \end{array}, \begin{array}{c} \bullet \\ \diagup \quad \diagdown \\ Y_2 \quad Y_1 \end{array}, \begin{array}{c} \bullet \\ \diagup \quad \diagdown \quad \diagup \quad \diagdown \\ Y_1 \quad Y_1 \quad Y_1 \quad Y_2 \end{array})$$

$$\frac{\partial H}{\partial Y} = \left(\begin{array}{cc} \frac{\partial H_1}{\partial Y_1} & \frac{\partial H_1}{\partial Y_2} \\ \frac{\partial H_2}{\partial Y_1} & \frac{\partial H_2}{\partial Y_2} \end{array} \right) = \left(\begin{array}{c} \begin{array}{c} \bullet \\ \diagup \quad \diagdown \\ Y_2 \quad Y_1 \end{array} \quad \begin{array}{c} \bullet \\ \diagup \quad \diagdown \\ Y_2 \quad Y_1 \end{array} \\ \begin{array}{c} \bullet \\ \diagup \quad \diagdown \quad \diagup \quad \diagdown \\ Y_2 \quad Y_1 \quad Y_1 \quad Y_2 \end{array} \quad \begin{array}{c} \bullet \\ \diagup \quad \diagdown \quad \diagup \quad \diagdown \\ Y_2 \quad Y_1 \quad Y_1 \quad Y_2 \end{array} \end{array} \right)$$

Newton combinatoire pour une seule équation

(Bergeron, Décoste, Labelle, Leroux)

$$\text{Itération : } Y_{k+1} = Y_k + (I - \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_k))^{-1}(H(Y_k) - Y_k)$$

$$Y_{k+1} = Y_k + \text{SEQ}(2\mathcal{Z}Y_k)(\mathcal{Z} + \mathcal{Z}Y_k^2 - Y_k)$$

$$Y_0 = 0 \quad Y_1 = \bullet \quad H(Y_1) - Y_1 = \mathcal{Z} + \mathcal{Z}Y_1^2 - Y_1 = \times \text{ } \text{ } \text{ } \text{ } \text{ }$$

$$Y_2 = \boxed{\begin{array}{c} \circ \\ \bullet \\ \bullet \end{array}} + \boxed{\begin{array}{c} 5 \\ \bullet \\ \bullet \\ \bullet \\ \bullet \end{array}} + \dots + \dots + \dots + \dots$$

$$Y_3 = \boxed{Y_2 + \begin{array}{c} \bullet \\ \bullet \\ \bullet \\ \bullet \end{array} + \dots + \begin{array}{c} \bullet \\ \bullet \\ \bullet \\ \bullet \end{array} + \dots + \dots + \dots}$$

Newton combinatoire pour une seule équation

(Bergeron, Décoste, Labelle, Leroux)

$$\text{Itération : } Y_{k+1} = Y_k + (I - \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_k))^{-1}(H(Y_k) - Y_k)$$

$$Y_{k+1} = Y_k + \text{SEQ}(2\mathcal{Z}Y_k)(\mathcal{Z} + \mathcal{Z}Y_k^2 - Y_k)$$

$$Y_0 = 0 \quad Y_1 = \bullet \quad H(Y_1) - Y_1 = \mathcal{Z} + \mathcal{Z}Y_1^2 - Y_1 = \times \text{ } \text{ } \text{ } \text{ } \text{ }$$

$$Y_2 = \boxed{\bullet + \bullet} + \dots + \dots + \dots + \dots$$

$$Y_3 = \boxed{Y_2 + \bullet + \dots + \dots + \dots + \dots} + \dots$$

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$$\text{Itération : } Y_{k+1} = Y_k + \left(I - \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_k) \right)^{-1} (H(Y_k) - Y_k)$$

$$Y_{k+1} = Y_k + \text{SEQ}(2\mathcal{Z}Y_k)(\mathcal{Z} + \mathcal{Z}Y_k^2 - Y_k)$$

$$Y_0 = 0 \qquad Y_1 = \bullet \qquad H(Y_1) - Y_1 = \mathcal{Z} + \mathcal{Z}Y_1^2 - Y_1 = \textcolor{red}{\times} \textcolor{blue}{\text{•}}$$

$$Y_2 = \boxed{\text{•}} + \boxed{\text{•}} + \dots + \dots + \dots + \dots$$

Diagram illustrating the computation of Y_2 . The first term is a single node (bullet). The second term is a node connected to two nodes, one of which is also connected to another node. This pattern continues with more complex connected components, each enclosed in a blue box labeled with a circled number (5, 13, etc.). Ellipses indicate intermediate terms.

$$Y_3 = \boxed{Y_2 + \text{•} + \dots + \text{•} + \dots + \text{•} + \dots + \dots}$$

Diagram illustrating the computation of Y_3 . It shows the addition of Y_2 to various terms. The first term is Y_2 plus a node connected to three nodes. Subsequent terms involve more complex connected components, each enclosed in a blue box labeled with a circled number (13, etc.). Ellipses indicate intermediate terms.

Newton combinatoire pour une seule équation

(Bergeron, Décoste, Labelle, Leroux)

$$\text{Itération : } Y_{k+1} = Y_k + \left(I - \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_k) \right)^{-1} (H(Y_k) - Y_k)$$

$$Y_{k+1} = Y_k + \text{SEQ}(2\mathcal{Z}Y_k)(\mathcal{Z} + \mathcal{Z}Y_k^2 - Y_k)$$

$$Y_0 = 0 \quad Y_1 = \bullet \quad H(Y_1) - Y_1 = \mathcal{Z} + \mathcal{Z}Y_1^2 - Y_1 = \text{red cross} \bullet$$

$$Y_2 = \begin{array}{c} \text{Diagram showing terms for } Y_2 \\ \text{involving } \mathcal{Z} \text{ and } \mathcal{Z}Y_1^2. \end{array} + \begin{array}{c} \text{Diagram showing terms for } Y_2 \\ \text{involving } \mathcal{Z} \text{ and } \mathcal{Z}Y_1^2. \end{array} + \dots + \dots + \dots + \dots$$

$$Y_3 = Y_2 + \begin{array}{c} \text{Diagram showing terms for } Y_3 \\ \text{involving } \mathcal{Z} \text{ and } \mathcal{Z}Y_1^2. \end{array} + \dots + \begin{array}{c} \text{Diagram showing terms for } Y_3 \\ \text{involving } \mathcal{Z} \text{ and } \mathcal{Z}Y_1^2. \end{array} + \dots + \dots + \dots + \dots$$

Newton pour un système

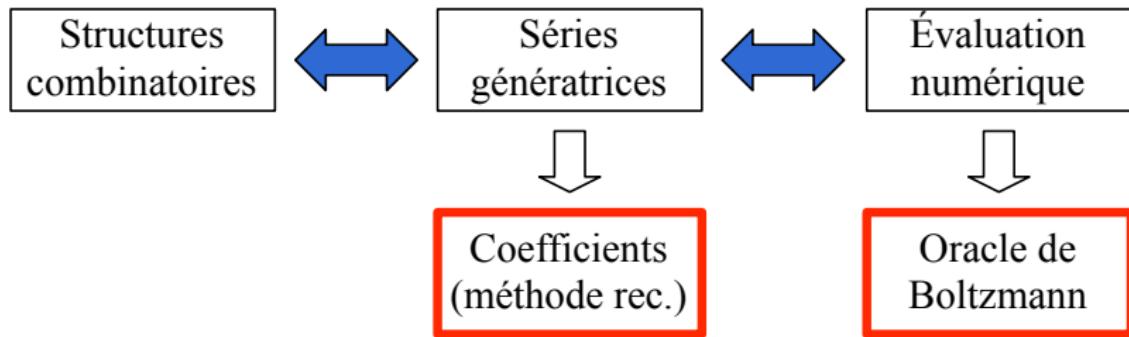
$$\text{Itération : } Y_{k+1} = Y_k + \boxed{\left(I - \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_k) \right)^{-1} (H(Y_k) - Y_k)}$$

- une seule équation → séquence
 - plusieurs équations → éclosions combinatoires (Labelle)
-

Newton pour un système

Itération : $Y_{k+1} = Y_k + \boxed{(I - \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_k))^{-1}(H(Y_k) - Y_k)}$

- une seule équation → séquence
- plusieurs équations → éclosions combinatoires (Labelle)



Newton optimisé

★ Optimisation :

- Newton combinatoire pour calculer $\mathbf{U} = (I - \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_k))^{-1}$

$$\mathbf{U}_{k+1} = \mathbf{U}_k + \mathbf{U}_k \mathbf{T}_{k+1}$$

$$\mathbf{T}_{k+1} = \boldsymbol{\beta}_k \mathbf{U}_k + \mathbf{T}_k^2$$

$$\boldsymbol{\beta}_k = \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_k) - \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_{k-1})$$

- à l'itération Y_k , faire une seule étape du calcul de \mathbf{U} .

★ Gain expérimental : 2 fois plus rapide.

Newton optimisé sur l'exemple

$$Y_{k+1} = Y_k + U_{k+1}(\mathcal{Z} + \mathcal{Z}Y_k^2 - Y_k)$$

$$U_{k+1} = U_k + U_k T_{k+1}$$

$$T_{k+1} = \beta_k U_k + T_k^2$$

$$\beta_k = 2\mathcal{Z}(Y_k - Y_{k-1})$$

$$Y_k + U_{k+1}(H(Y_k) - Y_k)$$

$$U_k + U_k T_{k+1}$$

$$\beta_k U_k + T_k^2$$

$$\frac{\partial H}{\partial Y}(\mathcal{Z}, Y_k) - \frac{\partial H}{\partial Y}(\mathcal{Z}, Y_{k-1})$$

$$Y_0 = 0 \quad Y_1 = \bullet$$

$$Y_2 = \circ \quad \begin{array}{c} \text{---} \\ \bullet \end{array} \quad \begin{array}{c} \text{---} \\ \bullet \end{array} \quad \begin{array}{c} \text{---} \\ \bullet \end{array}$$

$$Y_3 = Y_2 + \begin{array}{c} \text{---} \\ \bullet \end{array} \quad \dots \quad \begin{array}{c} \text{---} \\ \bullet \end{array}$$

Expérimentations – Extensions – Perspectives

- prototype en maple
 - → bibliothèque (maple et/ou autre langage)
 - grammaires jouet,
 - grammaires XML, $\sim 10^3$ équations (A. Darrasse),
 - tests (cf. exposé A. Denise),
 - autre ?
- en cours...
 - extension aux \mathcal{E} ,
 - substitution,
 - autres opérateurs.
- prochaines étapes
 - accélération de convergence,
 - calcul de singularité,
 - choix du paramètre en fonction de la taille visée.