

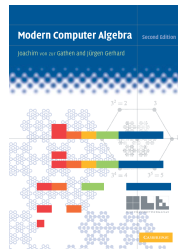
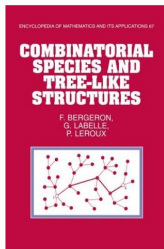
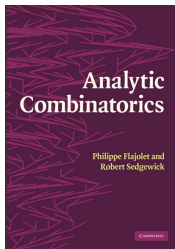
Algorithms for Combinatorial Systems: Between Analytic Combinatorics and Species Theory.

Carine Pivoteau - LIGM - december 2011

joint work with [Bruno Salvy](#) and [Michèle Soria](#)

I Introduction

Context



Aim: Algorithms for analytic combinatorics.
Well-defined input provided by species theory.
Efficiency by computer algebra.

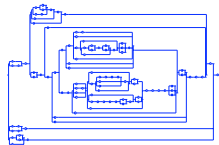
Bonus: Unified framework for constructible combinatorial classes.

A small set of species

- \mathcal{E} (or 1), \mathcal{Z} , \times , $+$, SEQ , SET , CYC ,
- cardinality constraints that are finite unions of intervals,
- can be used recursively (implicit systems).

Examples:

- Regular languages
- Unambiguous context-free languages
- Trees ($\mathcal{B} = \mathcal{Z} + \mathcal{Z} \times \mathcal{B}^2$, $\mathcal{T} = \mathcal{Z} \times \text{SET}(\mathcal{T})$)
- Mappings, ...



Two related problems:

- 1 **Enumeration**: number of objects of size n for $n = 0, 1, 2, \dots$
- 2 **Random sampling**: all objects of size n with the same proba.

Two contexts: labelled/unlabelled.

What do we need for Random Sampling?

We have:

- A combinatorial specification
- A recursive algorithm to compute structures
- Implicit equations on generating functions

$$\begin{cases} \mathcal{S} &= \text{SEQ}(\mathcal{Z} + \mathcal{P}), \\ \mathcal{P} &= \text{SET}_{>0}(\mathcal{Z} + \mathcal{S}). \end{cases}$$

$$\begin{cases} S(z) &= 1/(1 - (z + P(z))), \\ P(z) &= \exp(z + S(z)) - 1. \end{cases}$$

or

$$P(z) = \exp(\sum_{k \geq 0} (z^k + S(z^k))/k) - 1.$$

We need:

- **Recursive Method** (Flajolet, Zimmerman, Van Cutsem 94):
 - ▷ **Enumeration sequences** for each class of the specification.
- **Boltzmann Method** (Duchon *et al.* 04):
 - ▷ A **Numerical Oracle** that gives values of the gfs at a given (well chosen) point.
 - ▷ Ultimately, a way to evaluate the **singularities** of the gfs.

Oracle \equiv solving large systems?

The generating series are given by implicit systems of equations.

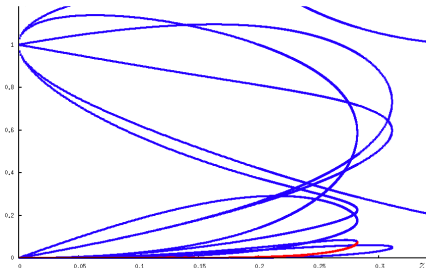
We need:

- **only one solution;**
- **the right one;**
- **only numerically.**

In the worst case, these requirements would make no difference.

But these systems inherit **structure** from combinatorics.

▷ Even more complicated in the **unlabeled** case.



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```
sys := [ C0 = x C1 C2 C3 (C1 + C3), Z = x, C1 = x
+ x / (1 - C1^2 C3^2), C2 = 2x + x / ((1 - x C1^2 C2^2) (1 - C2)),
C3 = x + x (3x + x^2 + x^2 C1 C3) / (1 - C1^2) ]
> [seq(subs(t,C0),t=solve(subs(x=0.1,sys)))]
[0.0003125169973, 0.0007429960174, 0.01391132169,
-0.01391089776, 0.06534819752, 0.1516695772,
0.5931967039, -0.5909308297, -0.002843524044,
-0.006587551424, -0.02496904471, 0.02486320262,
1.016379119, 0.2631789750 + 0.1384080116 I,
-0.3391146531, 0.2631789750 - 0.1384080116 I,
-0.002894993353, -0.006718005666, -0.02619777844,
0.02609673139, -0.07632515320, -0.1768253273,
-0.6704728314, 0.6676342030, 1.015911152, 0.2617092228
+ 0.1379131433 I, -0.3359391708, 0.2617092228
- 0.1379131433 I]
```

▷ Even more complicated in the **unlabeled** case.

Idea

By iteration

Numerical Oracle:
numerical iteration that converges
to the unique **relevant** solution

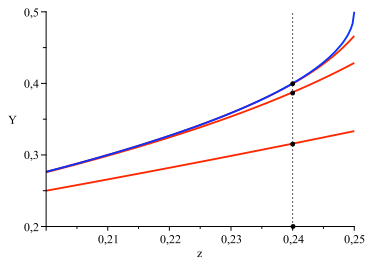
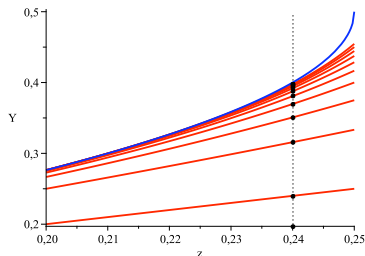


convergence of the iteration
on counting series



convergence of the iteration on
combinatorial functional systems

Fast oracle: Newton iteration



Binary trees: $B(z) = z + B(z)^2$

Results (1/2): Fast Enumeration

Theorem (Enumeration in Quasi-Optimal Complexity)

First N coefficients of gfs of **constructible species** in

- ① *arithmetic complexity:*
 - $O(N \log N)$ (both ogf and egf);
- ② *binary complexity:*
 - $O(N^2 \log^2 N \log \log N)$ (unlabeled, ogf);
 - $O(N^2 \log^3 N \log \log N)$ (labeled, egf).

▷ Quasi-optimal: linear with respect to the size of the output, up to possibly logarithmic factors.

▷ Very simple method, easy to implement.

Bonus : Differential Systems

$$\mathcal{Y}(\mathcal{Z}) = \mathcal{H}(\mathcal{Z}, \mathcal{Y}(\mathcal{Z})) + \int_0^{\mathcal{Z}} \mathcal{G}(\mathcal{T}, \mathcal{Y}(\mathcal{T})) d\mathcal{T}$$

Results (2/2): Oracle

- 1 The egfs and the ogfs of *constructible* combinatorial classes are **convergent** in the neighborhood of 0;
- 2 A **numerical iteration** converging to $\mathbf{Y}(\alpha)$ in the **labelled** case (α inside the disk);
▷ convergence asymptotically quadratic

- 3 A **numerical iteration** converging to the sequence

$$\mathbf{Y}(\alpha), \mathbf{Y}(\alpha^2), \mathbf{Y}(\alpha^3), \dots$$

in the **unlabeled** case (α inside the disk);
▷ hybrid algorithm;

... and also: a criterion to decide if α is inside the disk of cvg of \mathbf{Y} .

From Analytic Combinatorics to Species Theory

Analytic Combinatorics:

- Symbolic method to describe recursive combinatorial classes
- A restricted set of **combinatorial constructions**, with a dictionary for gfs.
- Powerful tools for enumeration (singularity analysis,...)
- Automatic methods for random generation (Recursive, Boltzmann)

But no well-founded systems...

Species Theory:

- A more general framework for combinatorial structures
- **Implicit species theorem**
- Labelle's work on the combinatorial derivative
- Combinatorial Newton iteration (Decoste, Labelle, Leroux)
- Combinatorial *differential systems*

But no analytic tools...

II Combinatorics

The key point

Theorem (Implicit Species Theorem (Joyal 81))

Let \mathcal{H} be a vector of *multisort species*, such that

- $\mathcal{H}(\mathbf{0}, \mathbf{0}) = \mathbf{0}$ and
- the Jacobian matrix $\partial\mathcal{H}/\partial\mathcal{Y}(\mathbf{0}, \mathbf{0})$ is nilpotent.

The system of equations

$$\mathcal{Y} = \mathcal{H}(\mathcal{Z}, \mathcal{Y})$$

admits a vector \mathcal{S} of *species solution* such that $\mathcal{S}(\mathbf{0}) = \mathbf{0}$, which is *unique up to isomorphism*.

- What do the bold symbols mean?
- $\mathcal{H}(\mathbf{0}, \mathbf{0}) = \mathbf{0}$?
- What about the other condition?
- Why is it so important?

Short introduction to Species

Definition (Species \mathcal{F})

finite set $U \mapsto$ finite set $\mathcal{F}[U]$

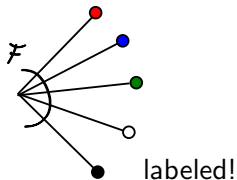
bij. $\sigma : U \rightarrow V \mapsto$ bij. $\mathcal{F}[\sigma] : \mathcal{F}[U] \rightarrow \mathcal{F}[V]$

Examples:

- $0, 1, \mathbb{Z}$;
- SET;
- SEQ, CYC.

Short introduction to Species

Species \mathcal{F} :

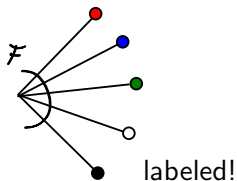


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Short introduction to Species

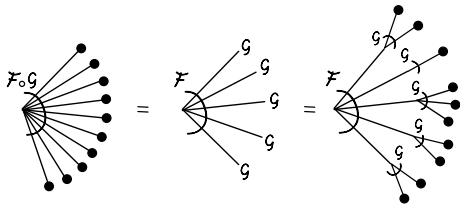
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Examples:

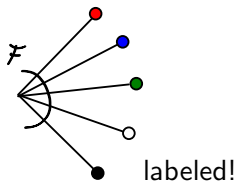
- $0, 1, \mathbb{Z}$;
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• Composition $\mathcal{F} \circ \mathcal{G}$:

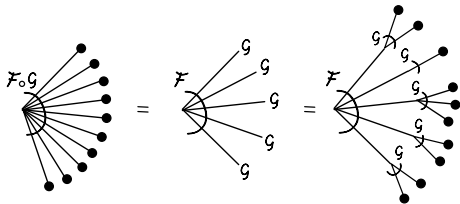


Short introduction to Species

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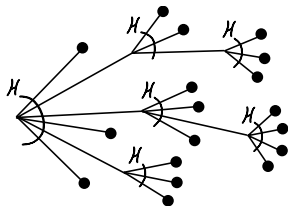
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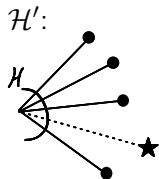
Examples:

- $0, 1, \mathbb{Z}$;
- SET;
- SEQ, CYC.

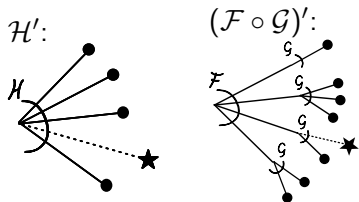
- $\mathcal{Y} = \mathcal{H}(\mathbb{Z}, \mathcal{Y})$



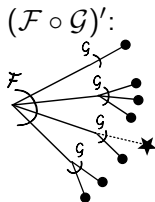
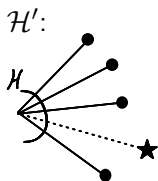
Derivative



Derivative

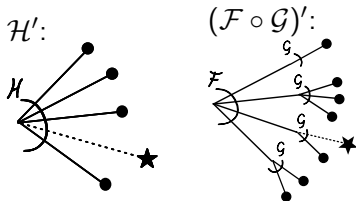


Derivative



| species | derivative |
|---------------------------------|--|
| $\mathcal{A} + \mathcal{B}$ | $\mathcal{A}' + \mathcal{B}'$ |
| $\mathcal{A} \cdot \mathcal{B}$ | $\mathcal{A}' \cdot \mathcal{B} + \mathcal{A} \cdot \mathcal{B}'$ |
| $\text{SEQ}(\mathcal{B})$ | $\text{SEQ}(\mathcal{B}) \cdot \mathcal{B}' \cdot \text{SEQ}(\mathcal{B})$ |
| $\text{CYC}(\mathcal{B})$ | $\text{SEQ}(\mathcal{B}) \cdot \mathcal{B}'$ |
| $\text{SET}(\mathcal{B})$ | $\text{SET}(\mathcal{B}) \cdot \mathcal{B}'$ |

Derivative



Example:

| species | derivative |
|-----------------|--|
| $A + B$ | $A' + B'$ |
| $A \cdot B$ | $A' \cdot B + A \cdot B'$ |
| $\text{SEQ}(B)$ | $\text{SEQ}(B) \cdot B' \cdot \text{SEQ}(B)$ |
| $\text{CYC}(B)$ | $\text{SEQ}(B) \cdot B'$ |
| $\text{SET}(B)$ | $\text{SET}(B) \cdot B'$ |

$$\mathcal{H}(\mathcal{G}, \mathcal{S}, \mathcal{P}) := (\mathcal{S} + \mathcal{P}, \text{SEQ}(\mathcal{Z} + \mathcal{P}), \text{SET}(\mathcal{Z} + \mathcal{S})).$$

$$\frac{\partial \mathcal{H}}{\partial \mathcal{Y}} = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & \text{SEQ}(\mathcal{Z} + \mathcal{P}) \cdot 1 \cdot \text{SEQ}(\mathcal{Z} + \mathcal{P}) \\ 0 & \text{SET}(\mathcal{Z} + \mathcal{S}) \cdot 1 & 0 \end{pmatrix}$$

Back to Joyal's Implicit Species Theorem

Theorem

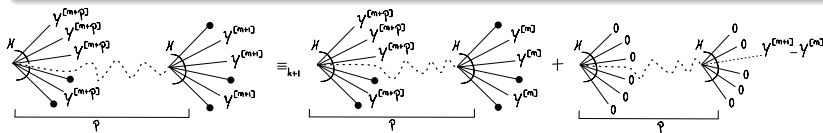
If $\mathcal{H}(\mathbf{0}, \mathbf{0}) = \mathbf{0}$ and $\partial\mathcal{H}/\partial\mathcal{Y}(\mathbf{0}, \mathbf{0})$ is nilpotent, then $\mathcal{Y} = \mathcal{H}(\mathcal{Z}, \mathcal{Y})$ has a unique solution, limit of

$$\mathcal{Y}^{[0]} = \mathbf{0}, \quad \mathcal{Y}^{[n+1]} = \mathcal{H}(\mathcal{Z}, \mathcal{Y}^{[n]}) \quad (n \geq 0).$$

Def. $\mathcal{A} =_k \mathcal{B}$ if they coincide up to size k (contact k).

Key Lemma

If $\mathcal{Y}^{[n+1]} =_k \mathcal{Y}^{[n]}$, then $\mathcal{Y}^{[n+p+1]} =_{k+1} \mathcal{Y}^{[n+p]}$, ($p = \text{dimension}$).



Combinatorial Newton Iteration

Theorem (essentially Labelle)

For any well-founded system $\mathcal{Y} = \mathcal{H}(\mathcal{Z}, \mathcal{Y})$, if \mathcal{A} has contact k with the solution and $\mathcal{A} \subset \mathcal{H}(\mathcal{Z}, \mathcal{A})$, then

$$\mathcal{A} + \sum_{i \geq 0} \left(\frac{\partial \mathcal{H}}{\partial \mathcal{Y}}(\mathcal{Z}, \mathcal{A}) \right)^i \cdot (\mathcal{H}(\mathcal{Z}, \mathcal{A}) - \mathcal{A})$$

has contact $2k + 1$ with it.

$$\mathcal{A} + \mathcal{A}^+ = \text{Diagram 1} + \text{Diagram 2} \quad \begin{cases} \mathcal{A} =_k \mathcal{Y}, \\ \mathcal{Y} - \mathcal{A}^+ =_k 0, \\ \mathcal{A} + \mathcal{A}^+ =_{2k+1} \mathcal{Y}, \end{cases}$$

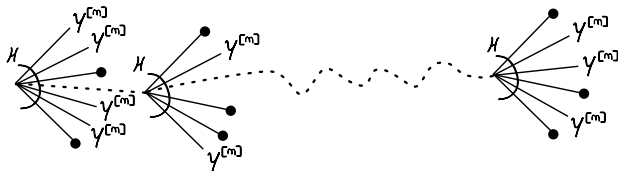
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has contact $2k + 1$ with it.



Rmk : Generation by increasing Strahler numbers.

$$\mathcal{Y}_{n+1} = \mathcal{Y}_n + \text{SEQ}(\mathcal{Z} \times \mathcal{Y}_n \times \star + \mathcal{Z} \times \star \times \mathcal{Y}_n) \times (1 + \mathcal{Z} \times \mathcal{Y}_n^2 - \mathcal{Y}_n).$$

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$$\mathcal{Y}_0 = 0 \quad \mathcal{Y}_1 = \circ$$

$$\mathcal{Y}_2 = \begin{array}{|c|} \hline \begin{array}{c} \circ \\ \bullet \end{array} \\ \hline \end{array} + \begin{array}{|c|} \hline \begin{array}{c} \bullet \end{array} \\ \hline \end{array} + \begin{array}{|c|} \hline \begin{array}{c} \bullet \end{array} \\ \hline \end{array} + \dots + \begin{array}{|c|} \hline \begin{array}{c} \bullet \end{array} \\ \hline \end{array} + \dots$$

(2)

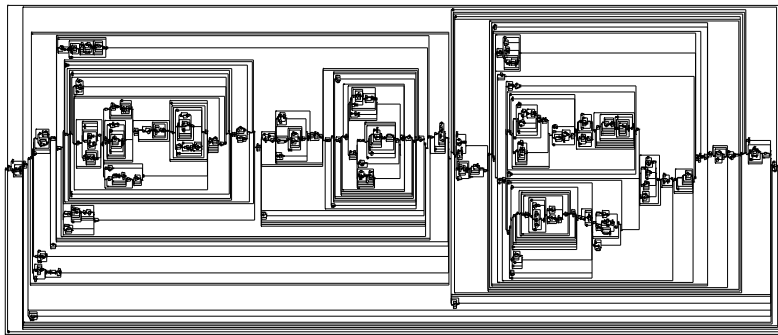
$$\mathcal{Y}_3 = \mathcal{Y}_2 + \begin{array}{|c|} \hline \begin{array}{c} \bullet \end{array} \\ \hline \end{array} + \dots + \begin{array}{|c|} \hline \begin{array}{c} \bullet \end{array} \\ \hline \end{array} + \dots + \begin{array}{|c|} \hline \begin{array}{c} \bullet \end{array} \\ \hline \end{array} + \dots$$

(6)

[Décoste, Labelle, Leroux 1982]

III Algorithms

Example: Series-Parallel Graphs



$$\begin{cases} \mathcal{G} &= \mathcal{S} + \mathcal{P}, \\ \mathcal{S} &= \text{SEQ}(\mathcal{Z} + \mathcal{P}), \\ \mathcal{P} &= \text{SET}_{>0}(\mathcal{Z} + \mathcal{S}). \end{cases} \quad \frac{\partial \mathcal{H}}{\partial \mathcal{Y}} = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & \text{SEQ}^2(\mathcal{Z} + \mathcal{P}) \\ 0 & \text{SET}(\mathcal{Z} + \mathcal{S}) & 0 \end{pmatrix}$$

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$$\begin{cases} G &= S + P, \\ S &= (1 - z - P)^{-1}, \\ P &= \exp(z + S) - 1. \end{cases} \quad \frac{\partial \mathbf{H}}{\partial \mathbf{Y}} = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & (1 - z - P)^{-2} \\ 0 & \exp(z + S) & 0 \end{pmatrix}$$

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Newton iteration: $\mathbf{Y}^{[n]} := \begin{pmatrix} G^{[n]} \\ S^{[n]} \\ P^{[n]} \end{pmatrix},$

$$\mathbf{Y}^{[n+1]} = \mathbf{Y}^{[n]} + \left(\text{Id} - \frac{\partial \mathbf{H}}{\partial \mathbf{Y}}(\mathbf{Y}^{[n]}) \right)^{-1} \cdot \left(\mathbf{H}(\mathbf{Y}^{[n]}) - \mathbf{Y}^{[n]} \right) \bmod z^{2^{n+1}}.$$

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\Rightarrow What about the inverse? And the exponential?

$$\begin{cases} G &= S + P, \\ S &= (1 - z - P)^{-1}, \\ P &= \exp(z + S) - 1. \end{cases} \quad \frac{\partial \mathbf{H}}{\partial \mathbf{Y}} = \begin{pmatrix} 0 & 1 & 1 \\ 0 & 0 & (1 - z - P)^{-2} \\ 0 & \exp(z + S) & 0 \end{pmatrix}$$

Newton iteration: $\mathbf{Y}^{[n]} := \begin{pmatrix} G^{[n]} \\ S^{[n]} \\ P^{[n]} \end{pmatrix},$

$$\begin{cases} U^{[n+1]} &= U^{[n]} + U^{[n]} \cdot \left(\frac{\partial \mathbf{H}}{\partial \mathbf{Y}}(\mathbf{Y}^{[n]}) \cdot U^{[n]} + \text{Id} - U^{[n]} \right) \bmod z^{2^n}, \\ \mathbf{Y}^{[n+1]} &= \mathbf{Y}^{[n]} + U^{[n+1]} \cdot \left(\mathbf{H}(\mathbf{Y}^{[n]}) - \mathbf{Y}^{[n]} \right) \bmod z^{2^{n+1}}. \end{cases}$$

$$\hat{Y}_2^{[0]}(z) = 0 \quad \hat{Y}_3^{[0]}(z) = 0$$

$$\hat{Y}_2^{[1]}(z) = z^2 + 3z^3 + \frac{29}{6}z^4 + \frac{139}{12}z^5 + \frac{3337}{120}z^6 + \frac{601}{9}z^7 + \frac{808243}{5040}z^8 + \dots$$

$$\hat{Y}_3^{[1]}(z) = \frac{1}{2}z^2 + \frac{7}{6}z^3 + \frac{61}{24}z^4 + \frac{721}{120}z^5 + \frac{10351}{720}z^6 + \frac{173867}{5040}z^7 + \frac{667957}{8064}z^8 + \dots$$

$$\hat{Y}_2^{[2]}(z) = z^2 + 3z^3 + \frac{61}{12}z^4 + \frac{29}{2}z^5 + \frac{15961}{360}z^6 + \frac{2841}{20}z^7 + \frac{9484021}{20160}z^8 + \dots$$

$$\hat{Y}_3^{[2]}(z) = \frac{1}{2}z^2 + \frac{7}{6}z^3 + \frac{73}{24}z^4 + \frac{1051}{120}z^5 + \frac{19381}{720}z^6 + \frac{436087}{5040}z^7 + \frac{11584693}{40320}z^8 + \dots$$

$$\hat{Y}_2^{[3]}(z) = z^2 + 3z^3 + \frac{61}{12}z^4 + \frac{29}{2}z^5 + \frac{15961}{360}z^6 + \dots + \frac{366558482492939101}{108972864000}z^{15} + \dots$$

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$$y^{[1]} = (0.1230510663209943063722\dots, \quad 0.06462664750711721439535\dots) \quad)$$

$$y^{[2]} = (0.1627000389319615796926\dots, \quad 0.09201293266034877734970\dots) \quad)$$

$$y^{[3]} = (0.1724333307003245710686\dots, \quad 0.09798441803578338336038\dots) \quad)$$

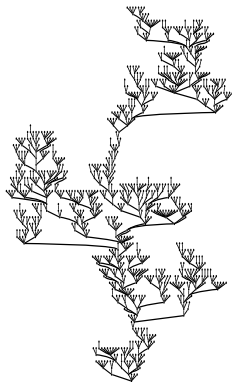
$$y^{[4]} = (0.1730460965507535353574\dots, \quad 0.09836831514307466499845\dots) \quad)$$

$$y^{[5]} = (0.1730486392973095133433\dots, \quad 0.09836989917963665326450\dots) \quad)$$

$$y^{[6]} = (0.1730486393408452105149\dots, \quad 0.09836989920678769126015\dots) \quad)$$

Example: Unlabelled Rooted Trees

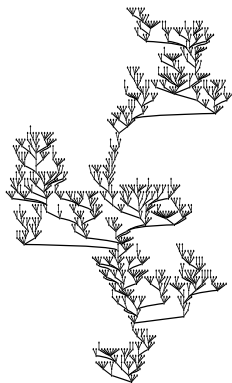
- ① Well-founded system: $\mathcal{Y} = \mathcal{Z} \cdot \text{SET}(\mathcal{Y}) =: \mathcal{H}(\mathcal{Z}, \mathcal{Y})$;



Example: Unlabelled Rooted Trees

- 1 Well-founded system: $\mathcal{Y} = \mathcal{Z} \cdot \text{SET}(\mathcal{Y}) =: \mathcal{H}(\mathcal{Z}, \mathcal{Y})$;
- 2 Combinatorial Newton iteration:

$$\mathcal{Y}^{[n+1]} = \mathcal{Y}^{[n]} + \text{SEQ}(\mathcal{H}(\mathcal{Y}^{[n]})) \cdot (\mathcal{H}(\mathcal{Y}^{[n]}) - \mathcal{Y}^{[n]})$$



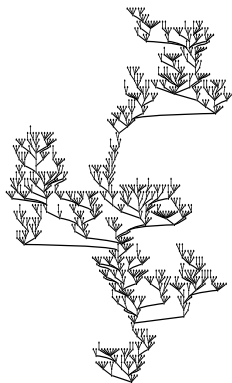
Example: Unlabelled Rooted Trees

- 1 Well-founded system: $\mathcal{Y} = \mathcal{Z} \cdot \text{SET}(\mathcal{Y}) =: \mathcal{H}(\mathcal{Z}, \mathcal{Y})$;
- 2 Combinatorial Newton iteration:

$$\mathcal{Y}^{[n+1]} = \mathcal{Y}^{[n]} + \text{SEQ}(\mathcal{H}(\mathcal{Y}^{[n]})) \cdot (\mathcal{H}(\mathcal{Y}^{[n]}) - \mathcal{Y}^{[n]})$$

- 3 OGF equation: $\tilde{Y}(z) = H(z, \tilde{Y}(z))$

$$\tilde{Y}(z) = z \exp(\tilde{Y}(z) + \frac{1}{2} \tilde{Y}(z^2) + \frac{1}{3} \tilde{Y}(z^3) + \dots)$$



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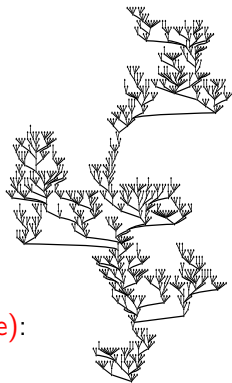
④ Newton for OGF (thanks to the combinatorial derivative):

$$\tilde{Y}^{[n+1]} = \tilde{Y}^{[n]} + \frac{H(z, \tilde{Y}^{[n]}) - \tilde{Y}^{[n]}}{1 - H(z, \tilde{Y}^{[n]})}$$

0,

$$z + z^2 + z^3 + z^4 + \dots,$$

$$z + z^2 + 2z^3 + 4z^4 + 9z^5 + 20z^6 + \dots$$



Example: Unlabelled Rooted Trees

① Well-founded system: $\mathcal{Y} = \mathcal{Z} \cdot \text{SET}(\mathcal{Y}) =: \mathcal{H}(\mathcal{Z}, \mathcal{Y})$;

② Combinatorial Newton iteration:

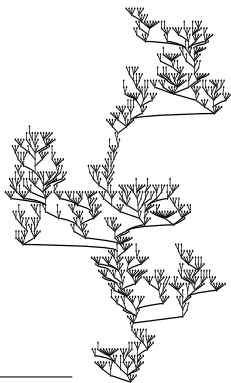
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④ Numerical iteration:

| n | $\tilde{Y}^{[n]}(0.3)$ | $\tilde{Y}^{[n]}(0.3^2)$ | $\tilde{Y}^{[n]}(0.3^3)$ |
|-----|------------------------|--------------------------|--------------------------|
| 0 | 0 | 0 | 0 |
| 1 | .43021322639 | 0.99370806338e-1 | 0.27759817516e-1 |
| 2 | .54875612912 | 0.99887132154e-1 | 0.27770629187e-1 |
| 3 | .55709557053 | 0.99887147197e-1 | 0.27770629189e-1 |
| 4 | .55713907945 | 0.99887147198e-1 | 0.27770629189e-1 |
| 5 | .55713908064 | 0.99887147198e-1 | 0.27770629189e-1 |



IV Well-founded combinatorial systems

The nature of combinatorial systems...

Joyal's Implicit Species Theorem is **too restrictive**:

- We don't want the condition $\mathcal{H}(\mathbf{0}, \mathbf{0}) = \mathbf{0}$.
- To allow equations such as $\mathcal{Y} = 1 + \mathcal{Z}\mathcal{Y}$.
- We want to *characterize precisely* which are the systems that define combinatorial structures ▷ **well-founded systems**.

Bonus :

A better understanding of the role played by the **Jacobian matrix** and a better knowledge of the **structure of combinatorial systems**.

General Implicit Species Theorem

Theorem (General Implicit Species Theorem)

Let $\mathcal{H} = (\mathcal{H}_{1:m})$ be **any** vector of species, such that the system $\mathcal{Y} = \mathcal{H}(\mathcal{Z}, \mathcal{Y})$ is **well-founded**. Then, this system admits a solution \mathcal{S} such that $\mathcal{S}(\mathbf{0}) = \mathcal{H}^m(\mathbf{0}, \mathbf{0})$, which is unique up to isomorphism.

Definition (Well-founded combinatorial system)

$\mathcal{Y} = \mathcal{H}(\mathcal{Z}, \mathcal{Y})$ is said to be *well-founded* when the iteration

$$\mathcal{Y}^{[0]} = \mathbf{0} \quad \text{and} \quad \mathcal{Y}^{[n+1]} = \mathcal{H}(\mathcal{Z}, \mathcal{Y}^{[n]}), \quad n \geq 0 \quad (\Phi)$$

is **well-defined**, defines a **convergent sequence** and the limit \mathcal{S} of this sequence has **no zero coordinate**.

Algorithmic Characterization

Definition

Companion system of $\mathcal{Y} = \mathcal{H}(\mathcal{Z}, \mathcal{Y})$:

$$\mathcal{Y} = \mathcal{K}(\mathcal{Z}_1, \mathcal{Z}, \mathcal{Y}), \quad \text{where} \quad \mathcal{K} = \mathcal{H}(\mathcal{Z}, \mathcal{Y}) - \mathcal{H}(\mathbf{0}, \mathbf{0}) + \mathcal{Z}_1 \mathcal{H}(\mathbf{0}, \mathbf{0}).$$

Theorem (Characterization of well-founded systems)

Let $\mathcal{H} = (\mathcal{H}_{1:m})$ be a vector of species. The combinatorial system $\mathcal{Y} = \mathcal{H}(\mathcal{Z}, \mathcal{Y})$ is well-founded **if and only if**

- ① the companion system $\mathcal{Y} = \mathcal{K}(\mathcal{Z}_1, \mathcal{Z}, \mathcal{Y})$ is well-founded at $\mathbf{0}$
- ② if $\mathcal{S}_1(\mathcal{Z}_1, \mathcal{Z})$ is the solution of $\mathcal{Y} = \mathcal{K}(\mathcal{Z}_1, \mathcal{Z}, \mathcal{Y})$ with $\mathcal{S}_1(\mathbf{0}, \mathbf{0}) = \mathbf{0}$, then $\mathcal{S}_1(\mathcal{Z}_1, \mathcal{Z})$ is polynomial in \mathcal{Z}_1 .

In this case, the limit of (Φ) is $\mathcal{S}_1(1, \mathcal{Z})$.

Joyal's conditions:

| | | |
|---|--|---|
| $\mathcal{Y} = \text{SEQ}(\mathcal{Z})$ ✓ | $\mathcal{Y} = \text{SEQ}(\mathcal{Z} \text{ SEQ}(\mathcal{Z}))$ ✓ | $\mathcal{Y} = \text{SEQ}(\text{SEQ}(\mathcal{Z}))$ ✗ |
| $\mathcal{H}'(0) = 0$ | $\mathcal{H}'(0) = 0$ | $\mathcal{H}'(0)$ not defined! |

| | | |
|---|---|---|
| $\mathcal{Y} = \mathcal{Z} \mathcal{Y}$ ✓ | $\mathcal{Y} = \mathcal{Z} + \mathcal{Z} \mathcal{Y}$ ✓ | $\mathcal{Y} = \mathcal{Z} + \mathcal{Y}$ ✗ |
| $\mathcal{H}'(0, 0) = 0$ | $\mathcal{H}'(0, 0) = 0$ | $\mathcal{H}'(0, 0) = 1$ |

Joyal's conditions:

$$\begin{array}{lll} \mathcal{Y} = \text{SEQ}(\mathcal{Z}) \quad \checkmark & \mathcal{Y} = \text{SEQ}(\mathcal{Z} \text{ SEQ}(\mathcal{Z})) \quad \checkmark & \mathcal{Y} = \text{SEQ}(\text{SEQ}(\mathcal{Z})) \quad \times \\ \mathcal{H}'(0) = 0 & \mathcal{H}'(0) = 0 & \mathcal{H}'(0) \text{ not defined!} \end{array}$$

$$\begin{array}{lll} \mathcal{Y} = \mathcal{Z} \mathcal{Y} \quad \checkmark & \mathcal{Y} = \mathcal{Z} + \mathcal{Z} \mathcal{Y} \quad \checkmark & \mathcal{Y} = \mathcal{Z} + \mathcal{Y} \quad \times \\ \mathcal{H}'(0, 0) = 0 & \mathcal{H}'(0, 0) = 0 & \mathcal{H}'(0, 0) = 1 \end{array}$$

With our conditions:

$$\mathcal{Y} = \mathcal{Z} \mathcal{Y} \quad \times \quad \text{because } \mathcal{Y} = 0.$$

How to detect 0 coordinates:

Look for 0 in $\mathcal{H}^m(\mathcal{Z}, 0)$.

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Look for 0 in $\mathcal{H}^m(\mathcal{Z}, \mathbf{0})$.

Examples:

$$\begin{array}{ll} \begin{cases} \mathcal{A} = \mathcal{B} \\ \mathcal{B} = \mathcal{C} \\ \mathcal{A} = \mathcal{Z} \end{cases} & \begin{cases} \mathcal{A} = \mathcal{B} \\ \mathcal{B} = \mathcal{Z} + \mathcal{C} \\ \mathcal{A} = \mathcal{Z}\mathcal{C} \end{cases} \end{array}$$

$$\begin{cases} \mathcal{Y}_1 = \mathcal{Z} \mathcal{Y}_2 \\ \mathcal{Y}_2 = \mathcal{Z} \mathcal{Y}_1 \text{ SEQ}(\mathcal{Y}_2) \end{cases} \quad \checkmark \quad \begin{pmatrix} 0 & 0 \\ \mathcal{Z} \text{ SEQ}(\mathcal{Y}_2) & \mathcal{Z} \mathcal{Y}_1 \text{ SEQ}(\mathcal{Y}_2)^2 \end{pmatrix} \Big|_{0,0} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

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$$\begin{cases} \mathcal{Y}_1 = \mathcal{Z} + \mathcal{Y}_2^2 \\ \mathcal{Y}_2 = \mathcal{Y}_1 \end{cases} \quad \checkmark \quad \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

Definition

$\mathcal{F}(\mathcal{Z}_1, \mathcal{Z}_2)$ is polynomial in the sorts \mathcal{Z}_1 when, for all $n \geq 0$, the species $\mathcal{F}_{=(\cdot, n)} = \sum_{k \geq 0} \mathcal{F}_{=(k, n)}$ is polynomial.

Examples:

- $\text{SEQ}(\mathcal{Z}_1 + \mathcal{Z}_2)$: not polynomial in \mathcal{Z}_1 or \mathcal{Z}_2
- $\text{SEQ}(\mathcal{Z}_1 \cdot \mathcal{Z}_2)$: polynomial in \mathcal{Z}_1 and \mathcal{Z}_2 (but not in \mathcal{Z})
- $\mathcal{Z}_1 \text{SEQ}(\mathcal{Z}_2)$: polynomial in \mathcal{Z}_1 and not in \mathcal{Z}_2 .

Well-founded Systems?

$$\begin{cases} \mathcal{Y}_1 = \mathcal{Z} + \mathcal{Y}_1 \mathcal{Y}_2 \\ \mathcal{Y}_2 = 1 \end{cases}$$

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Well-founded Systems?

$$\begin{cases} \mathcal{Y}_1 = \mathcal{Z} + \mathcal{Y}_1 \mathcal{Y}_2 \\ \mathcal{Y}_2 = \mathcal{Z}_1 \end{cases} \quad \text{✗}$$

$$\begin{cases} \mathcal{Y}_1 = \mathcal{Z} + \mathcal{Y}_2 \mathcal{Y}_1^2 \\ \mathcal{Y}_2 = \mathcal{Z}_1 \end{cases} \quad \text{✓}$$

Information given by the Jacobian Matrix

Role of the Jacobian Matrix:

- ① Well-founded systems at $\mathbf{0}$: nilpotence of $\partial\mathcal{H}/\partial\mathcal{Y}(\mathbf{0}, \mathbf{0})$
- ② Implicit polynomial species: nilpotence of $\partial\mathcal{H}/\partial\mathcal{Y}(\mathcal{Z}, \mathcal{Y})$
- ③ Implicit partially polynomial species:
nilpotence of $\partial\mathcal{H}/\partial\mathcal{Y}(\mathcal{Z}_1, \mathbf{0}, \mathcal{S}(\mathcal{Z}_1, \mathbf{0}))$
(+ conditions on \mathcal{H} and $\mathcal{S}(\mathcal{Z}_1, \mathbf{0})$)
- ④ Well-founded systems: both 1 and 3.
- ⑤ The key for Newton iteration.

But no information on the 0 coordinates.

What's next?

Use this to compute gfs singularities...