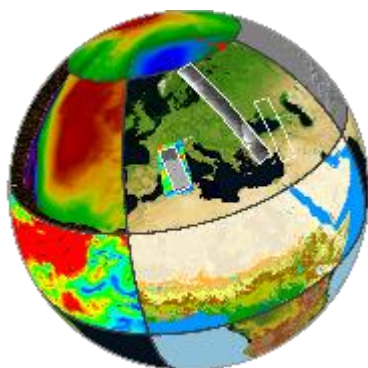


DEMIX SG3 – “Platforms and processing”

Presentation of studies



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- ❑ Presentation of VisioTerra
- ❑ VtWeb and “Data Processing Relay” (DPR)
- ❑ Presentation of EDAP and EDAP+

➤ Study 1 - Quality Assessment for Global DEM

- ❑ SRTM, ASTER GDEM, ALOS World 3D
- ❑ ICESat-1 / GLAS LiDAR
- ❑ Product Quality Evaluation Matrix
- ❑ Effects of DEM differences on orthorectification

➤ Study 2 - Quality Assessment for Copernicus DEM

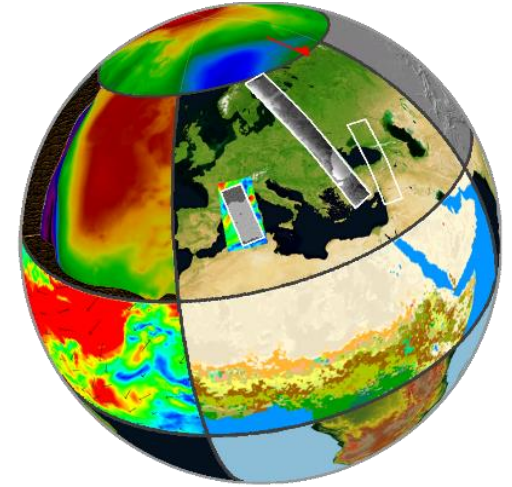
- ❑ Copernicus DEMs EEA-10, GLO-30, GLO-90
- ❑ 3 LiDAR: ICESat-1 / GLAS, ICESat-2 / ATLAS, GEDI (and 5 returns)
- ❑ Analysis of height errors according to LiDAR modes
- ❑ Comparison of COP-DEM with SRTM, ASTER GDEM and ALOS Word 3D (study 1)
- ❑ Spatial distribution of COP-DEM
- ❑ Influence of LULC (C3S-LC) on height errors
- ❑ COP-DEM is between the terrain (DTM) and the surface (DSM)

➤ Study 3 - Planimetric Misregistration Assessment

- ❑ See [Technical Note on Planimetric Misregistration Assessment](#)

➤ Study 4 - Sentinel-1 ARD from VHR DEM

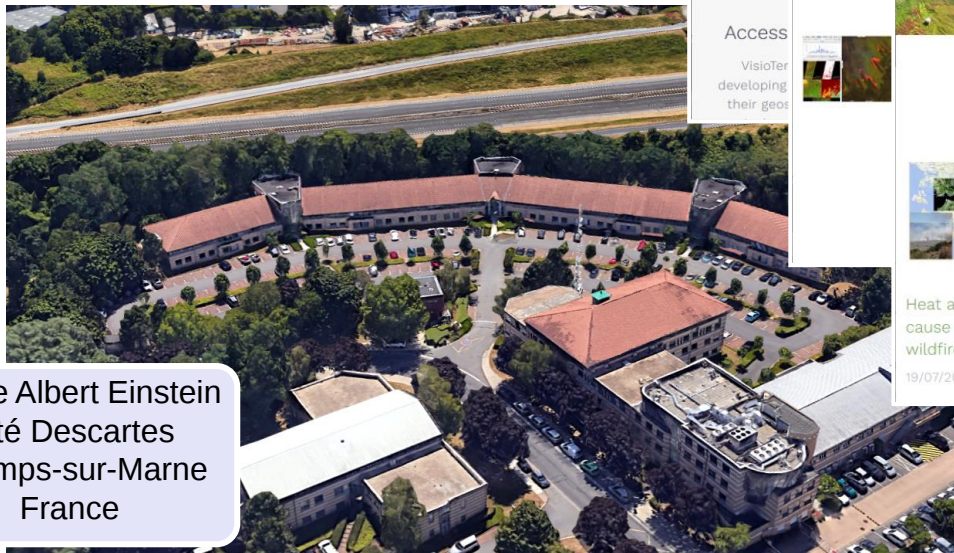
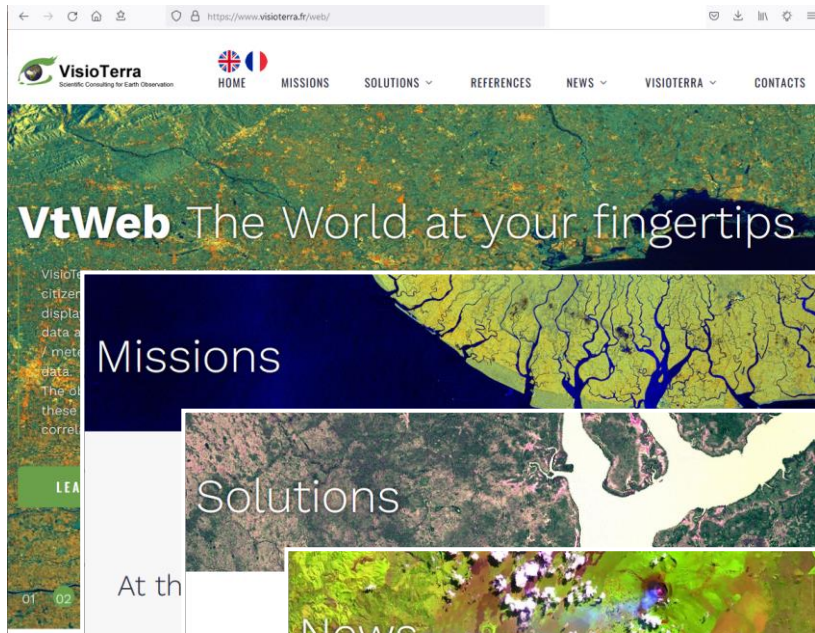
- ❑ See [Technical Note on Sentinel-1 ARD from VHR DEM](#)



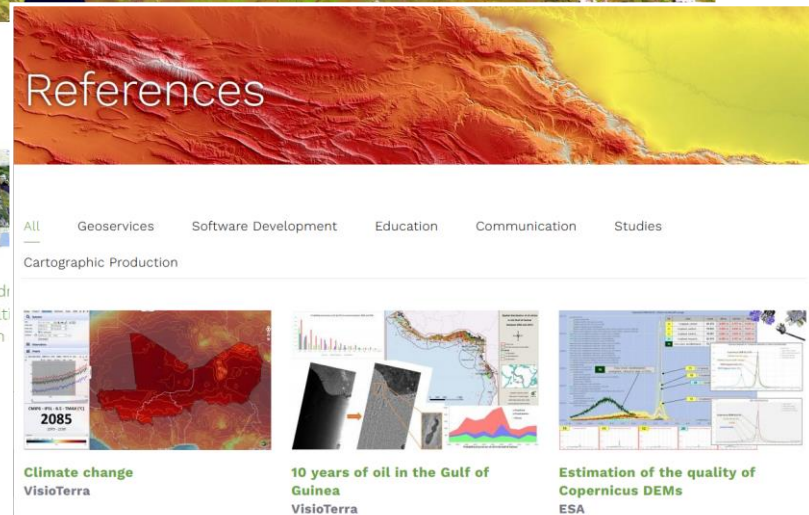


VisioTerra in few numbers

- Founded in May 2004
- 11 engineers
- Projects
 - ❑ **ESA** - Studies, Platforms CryoSat / Heritage and TPM missions, Outreach "Sentinel Vision"
 - ❑ **In Africa** - EU / NGOs - Platforms / Geoservices / Cartography / Training
- <https://visioterra.fr>



14 rue Albert Einstein
Cité Descartes
Champs-sur-Marne
France



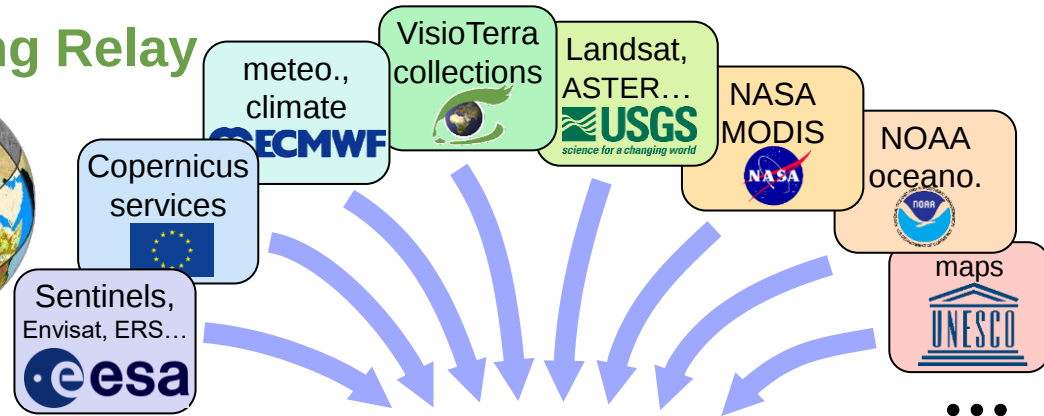
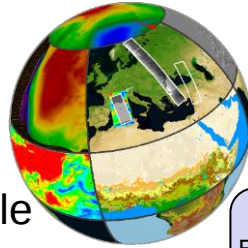


VtWeb – Data Processing Relay

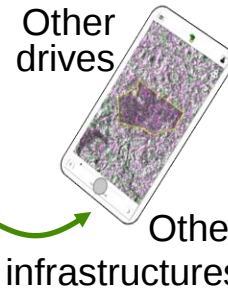
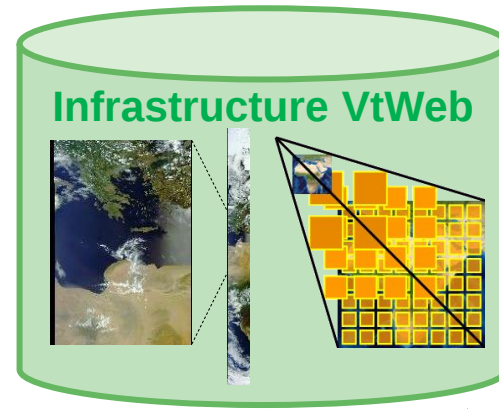
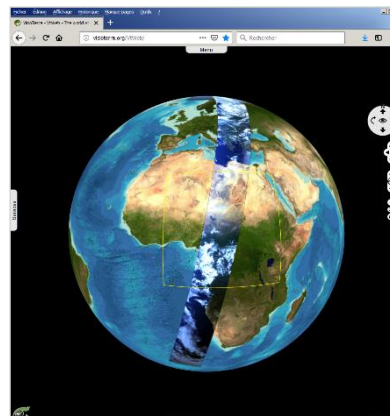
➤ VtWeb infrastructure

- ❑ 1 PB (1000 TB) available
 - 50 TB ASAR and ERS
 - 150 TB MERIS
- ❑ 1 Gb/s symmetric fibre
- ❑ 6 powerful servers

➤ DPR as a solution for Africa

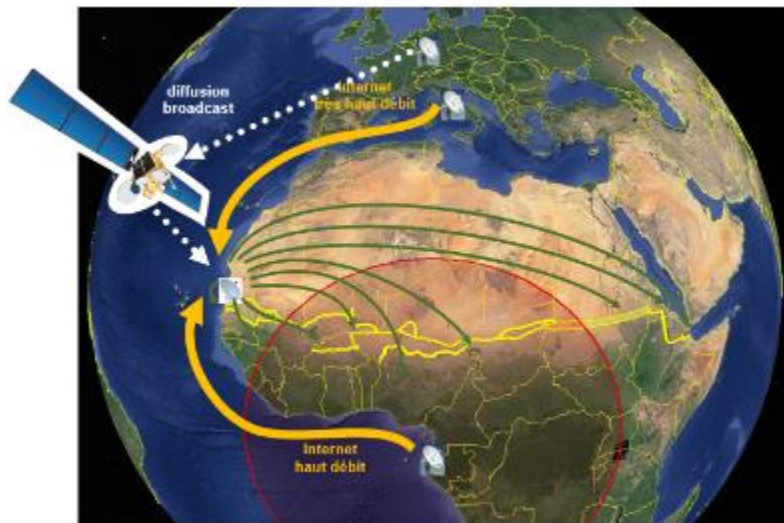
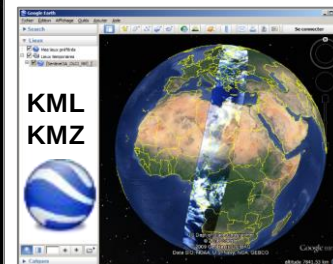


VtWeb client



Google Earth

G.I.S.





VtWeb - Client-server application

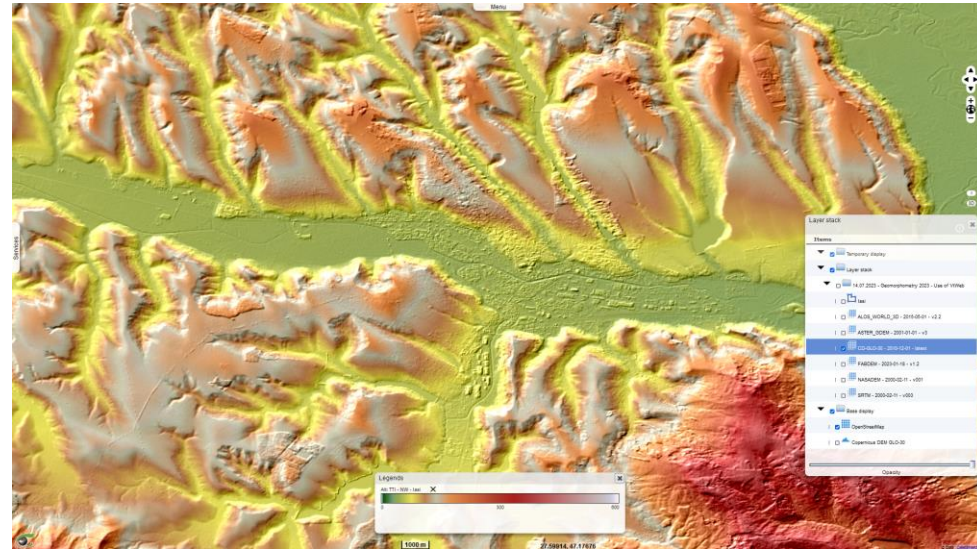
➤ Main features

- ❑ Open access without registration
- ❑ Many datasets in input (image, LiDAR, altimeter, vector fields...)
- ❑ Processing on-the-fly
- ❑ POF-ML macro-language
- ❑ Sharing with hyperlooks → [lasi 2D layer stack](#)
- ❑ Analysis tools
- ❑ Export

➤ Demonstration on Friday 14 morning

➤ Hyperlook documents

- ❑ [HYP-080-VtWeb-E SRTM ASTER-GDEM ALOS-World-3D comparison](#)
- ❑ [HYP-082-VtWeb-E SRTM ASTER-GDEM local statistics comparison](#)
- ❑ [HYP-086-VtWeb-E DEM impact on orthorectification](#)
- ❑ [HYP-087-VtWeb-E Presentation of ICESat-2 ATLAS](#)
- ❑ [HYP-089-VtWeb-E Comparison of DEMs in Chott Melghir Algeria](#)
- ❑ [HYP-091-VtWeb-E MERIT DEM first assessment](#)
- ❑ [HYP-094-VtWeb-E Assessment of slopes in Alaska LiDAR DEM](#)
- ❑ [HYP-095-VtWeb-E Comparison of Copernicus DEM releases 2020 vs 2019](#)
- ❑ [HYP-096-VtWeb-E Comparison of LiDAR GEDI vs ICESat-1 ICESat-2](#)
- ❑ [HYP-097-VtWeb-E NASADEM SRTMGL1 comparison](#)
- ❑ [HYP-098-VtWeb-E COP-DEM EU-DEM comparison](#)
- ❑ [HYP-099-VtWeb-E COP-DEM GLO-90 vs GLO-30 for Sentinel-2 orthorectification](#)
- ❑ [HYP-106-VtWeb-E Comparison of FABDEM releases 1.0 vs 1.2](#)
- ❑ [HYP-107-VtWeb-E Comparison of Copernicus DEM releases 2022 vs 2021](#)





EDAP / EDAP+ projects



➤ EDAP - Earthnet Data Assessment Pilot

- ❑ From 29.10.2018 to 04.11.2021 (3 years)
- ❑ Task 5 - Specific studies / Quality assessment of DEMs

➤ EDAP+

- ❑ KO on 06.07.2022
- ❑ Task 6 – DEM CLUSTER
- ❑ <https://earth.esa.int/eogateway/activities/edap/multi-mission-studies>

The screenshot shows the 'earth online' interface for the EDAP+ project. It includes a search bar, navigation tabs, and a main content area with an overview and related mission information. A grid of mission categories is displayed, with 'MULTI MISSION STUDIES AND DEM ASSESSMENTS' highlighted.

Global DEMs Documentation

- [Technical Note on Quality Assessment for Global DEM](#)

Copernicus DEM Documentation

- [Technical Note on Quality Assessment for Copernicus DEM](#)
- [Technical Note on Planimetric Misregistration Assessment](#)

VHR DEMs Documentation

- [Technical Note on VHR DEMs](#)
- [Technical Note on Sentinel-1 ARD from VHR DEM](#)



DEMIX SG3 “Platforms and processing”

➤ DEMIX

- ❑ KO on 17 July 2020
- ❑ Duties of SG3 “Platforms and processing”



Group 3: platforms and processing



Participants(11)*: C. Albinet, G. Amatulli, B. Bookhagen, C. Bielski, D. Gesch, F. Gascon, M. Hofton, M. Huber, J-P. Muller, J. Reinoso

CoLead: Z. Li, S. Riazanoff

Main tasks:

- lay out a viable workshare as a mix of products and geographical zones (DD: 2020/09/15)
- check compatibility of existing tools with methods set out by group 2 (DD: 2020/09/15)
- make available the applicable (f&o) DEM and validation data (DD: 2020/09/15)
- support the implementation of compatible tools where not already available (DD: 2020/10/15)
- perform test rounds with pilot areas and compare results (DD: 2020/11/15)
- run benchmarking (DGEG Level1) (DD: 2020/12/15)

*for colour codes of names see slide 4

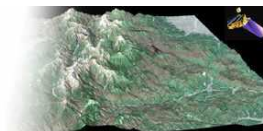
TMSG-DEMIX progress, July 17, 2020

11



Study 1 - Quality Assessment for Global DEM

➤ Global DEMs



➤ Product Quality Evaluation Matrix

Product Information	Product Generation	Ancillary Information	Uncertainty Characterisation	Validation
Product Details	Sensor Calibration & Characterisation Pre-Flight	Product Flags	Uncertainty Characterisation Method	Reference Data Representativeness
Availability & Accessibility	Sensor Calibration & Characterisation Post-Launch	Ancillary Data	Uncertainty Sources Included	Reference Data Quality
Product Format	Retrieval Algorithm Method		Uncertainty Values Provided	Validation Method
User Documentation	Retrieval Algorithm Tuning		Geolocation Uncertainty	Validation Results
Metrological Traceability Documentation	Additional Processing			

SRTM

Key
Not Assessed
Not Assessable
Basic
Intermediate
Good
Excellent



Information Not Public

Product Information	Product Generation	Ancillary Information	Uncertainty Characterisation	Validation
Product Details	Sensor Calibration & Characterisation Pre-Flight	Product Flags	Uncertainty Characterisation Method	Reference Data Representativeness
Availability & Accessibility	Sensor Calibration & Characterisation Post-Launch	Ancillary Data	Uncertainty Sources Included	Reference Data Quality
Product Format	Retrieval Algorithm Method		Uncertainty Values Provided	Validation Method
User Documentation	Retrieval Algorithm Tuning		Geolocation Uncertainty	Validation Results
Metrological Traceability Documentation	Additional Processing			

ASTER GDEM

Product Information	Product Generation	Ancillary Information	Uncertainty Characterisation	Validation
Product Details	Sensor Calibration & Characterisation Pre-Flight	Product Flags	Uncertainty Characterisation Method	Reference Data Representativeness
Availability & Accessibility	Sensor Calibration & Characterisation Post-Launch	Ancillary Data	Uncertainty Sources Included	Reference Data Quality
Product Format	Retrieval Algorithm Method		Uncertainty Values Provided	Validation Method
User Documentation	Retrieval Algorithm Tuning		Geolocation Uncertainty	Validation Results
Metrological Traceability Documentation	Additional Processing			

ALOS World 3D



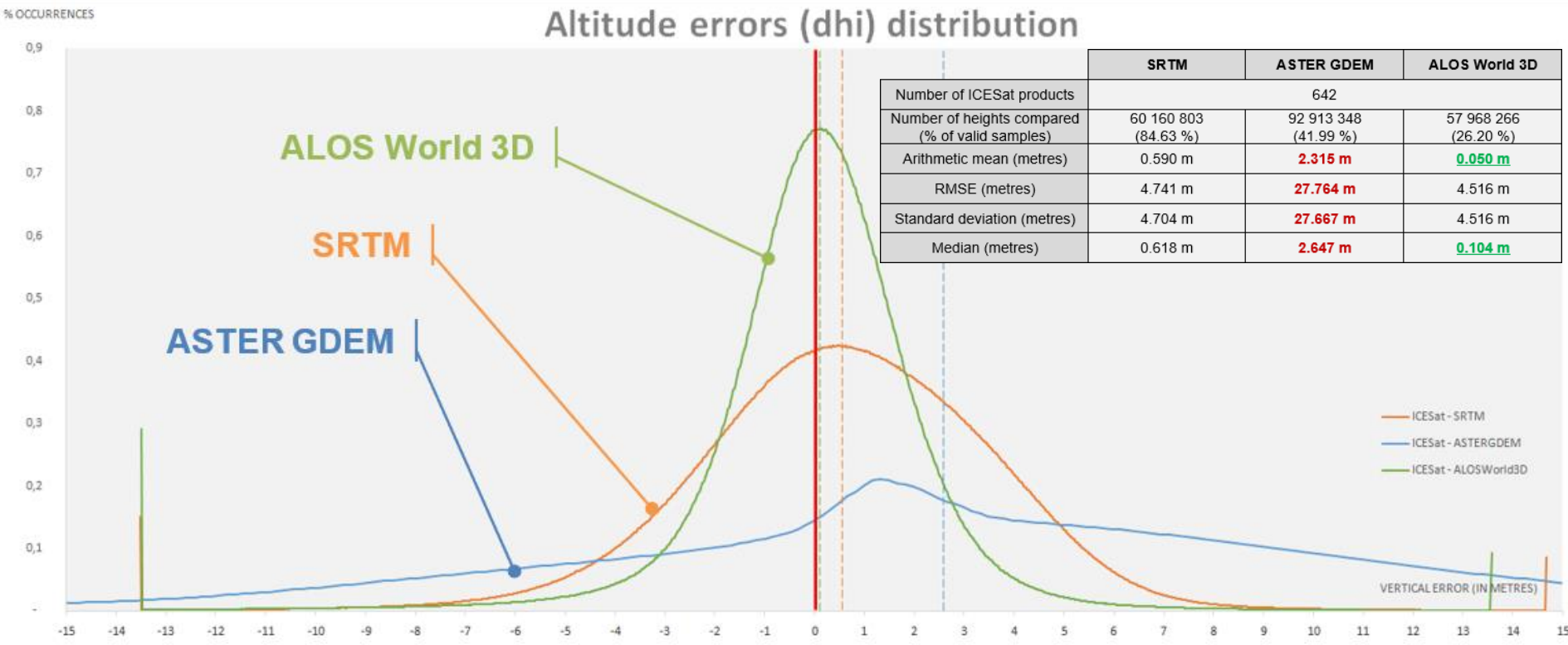
Study 1 - Computation of height differences



➤ Computation of differences (DEM height - ICESat-1 height)

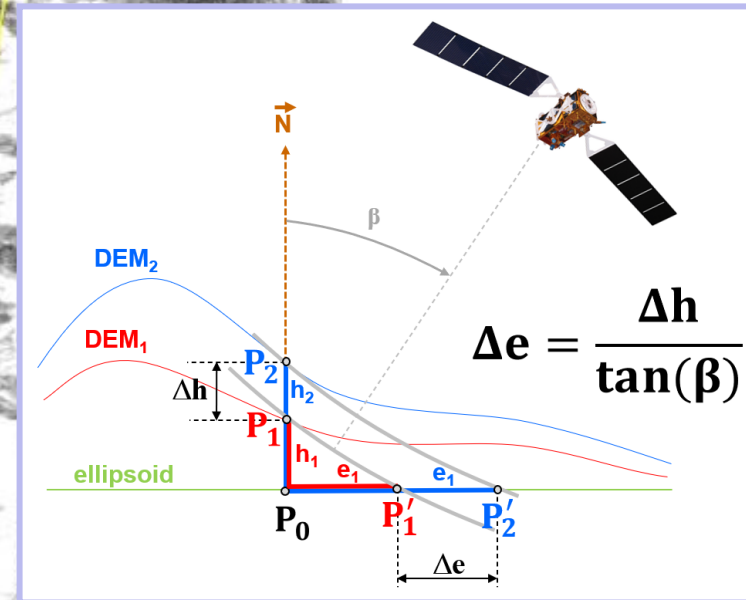
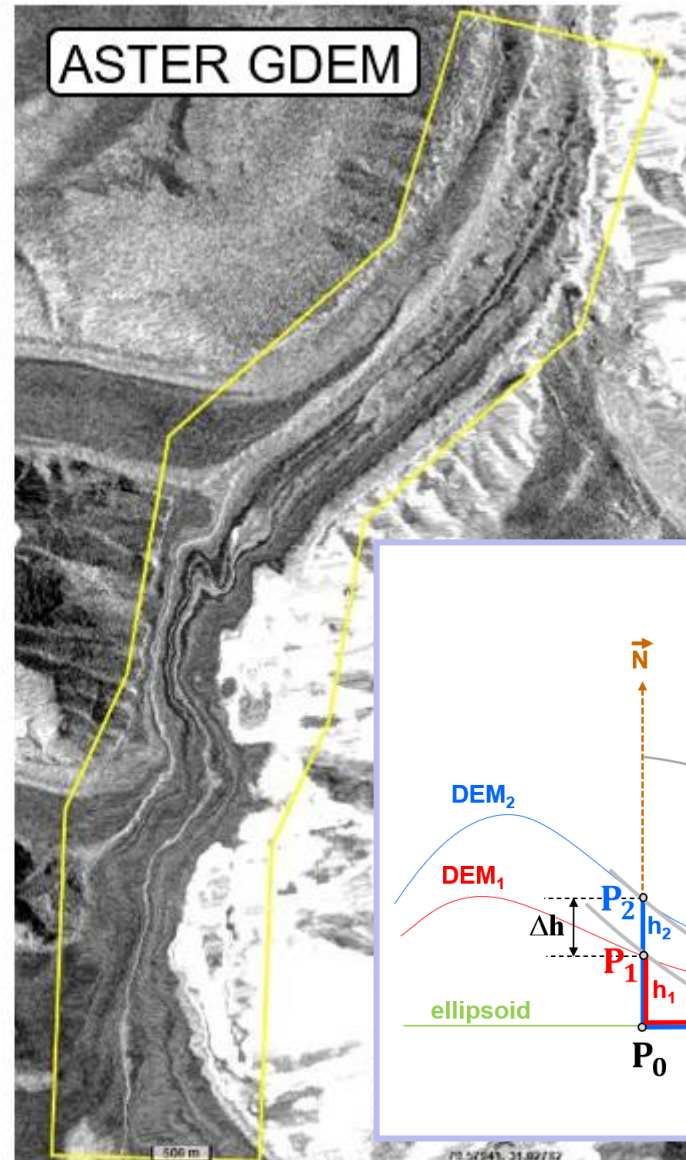
- ❑ ICESat-1 / GLAS / GLAH14 product - Filtering using quality flags (elev_use_flg, sat_corr_flg, elv_cloud_flg) - Conversion from TOPEX / Poseidon to WGS84 - Verification of collocation in flat areas
- ❑ Candidate DEMs - Change of VRS (Vertical Reference System) from EGM96 to WGS84

➤ Results of height differences





Study 1 - Effects of DEM differences on orthorectification





Study 2 - Copernicus DEMs EEA-10, GLO-30, GLO-90



Technical specification	ICESat-1	ICESat-2	GEDI
Instrument name	Geoscience Laser Altimeter System (GLAS)	Advanced Topographic Laser Altimeter System (ATLAS)	Global Ecosystem Dynamics Investigation (GEDI)
First acquisition date	02.20.2003	13.10.2018	25.03.2019
Last acquisition date	11.10.2009	Ongoing	Ongoing
Acquisition frequency	40 Hz	10 KHz / 70 Hz ¹	242 Hz
Ground sampling distance	~170 m	~0.7 m / 100 m ²	~60 m
Central wavelength	532 nm (green) / 1064 nm (near infrared)	532 nm (green)	1064 nm (near infrared)
Number of beams	1	6	8
Repeat cycle	Phase 1 – 8 days – [20/02/2003; 04/10/2003] Phase 2 – 91 days – [04/10/2003; 11/10/2009]	91 days	No repeat cycle
Footprint diameter	~70 m	~13 m / 100 m ³	~25 m

Product

GLAH14

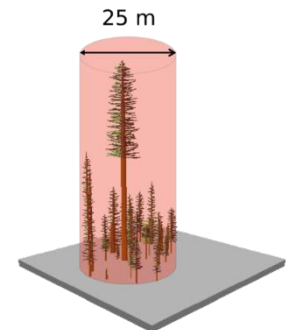
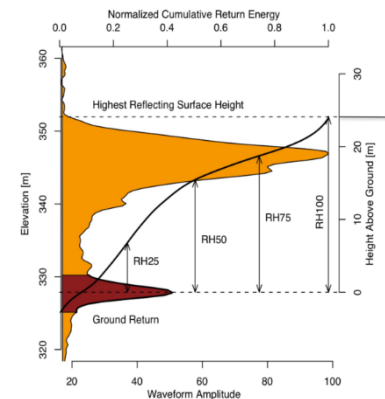
ATL08

GEDI02_A

Return / mode

terrain only
terrain with
canopy

lowest mode
highest return

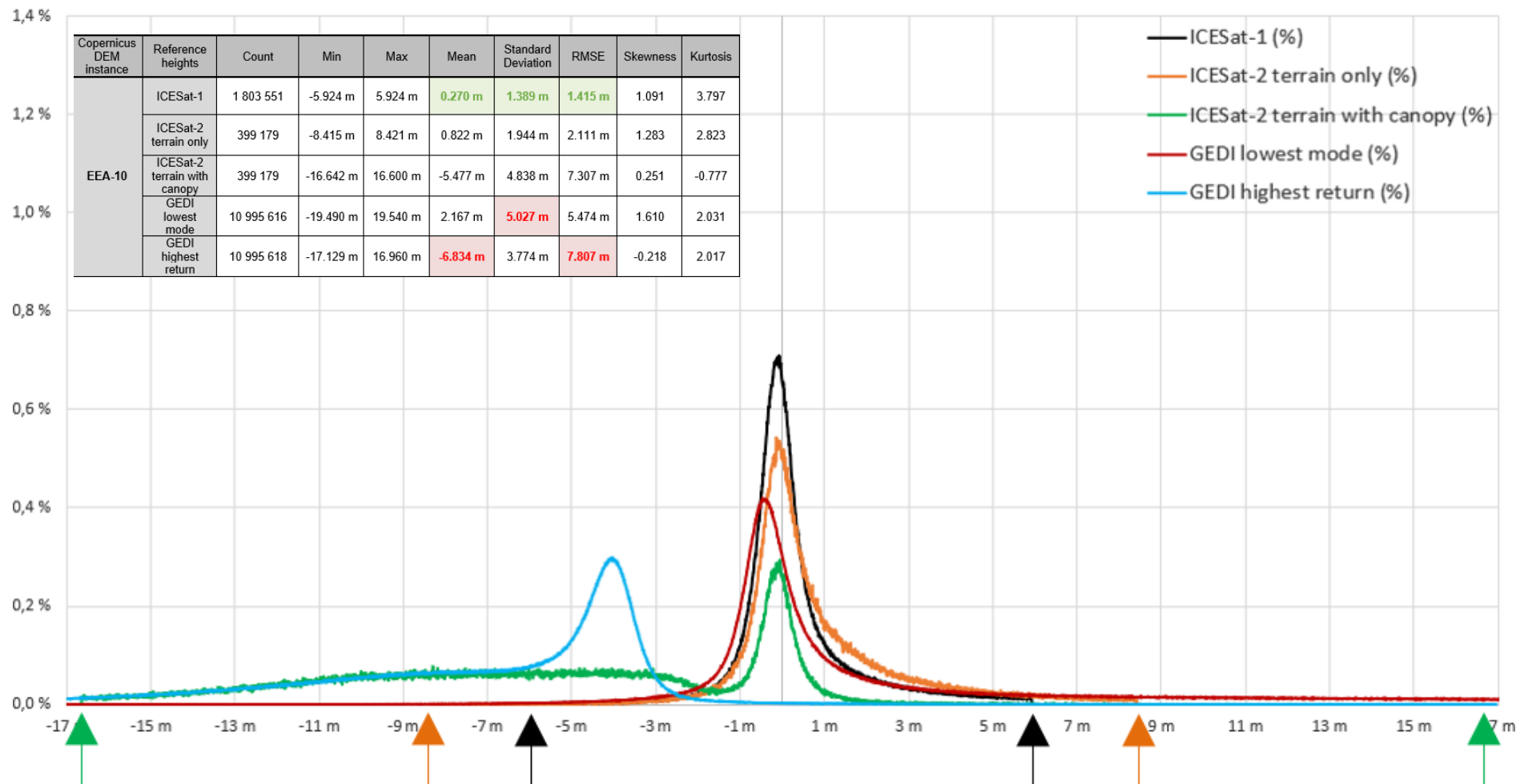




Study 2 - Height errors depending on LiDAR mission / mode

EEA-10

Copernicus DEM EEA-10 - Comparison with ICESat-1, ICESat-2 and GEDI (LE95)

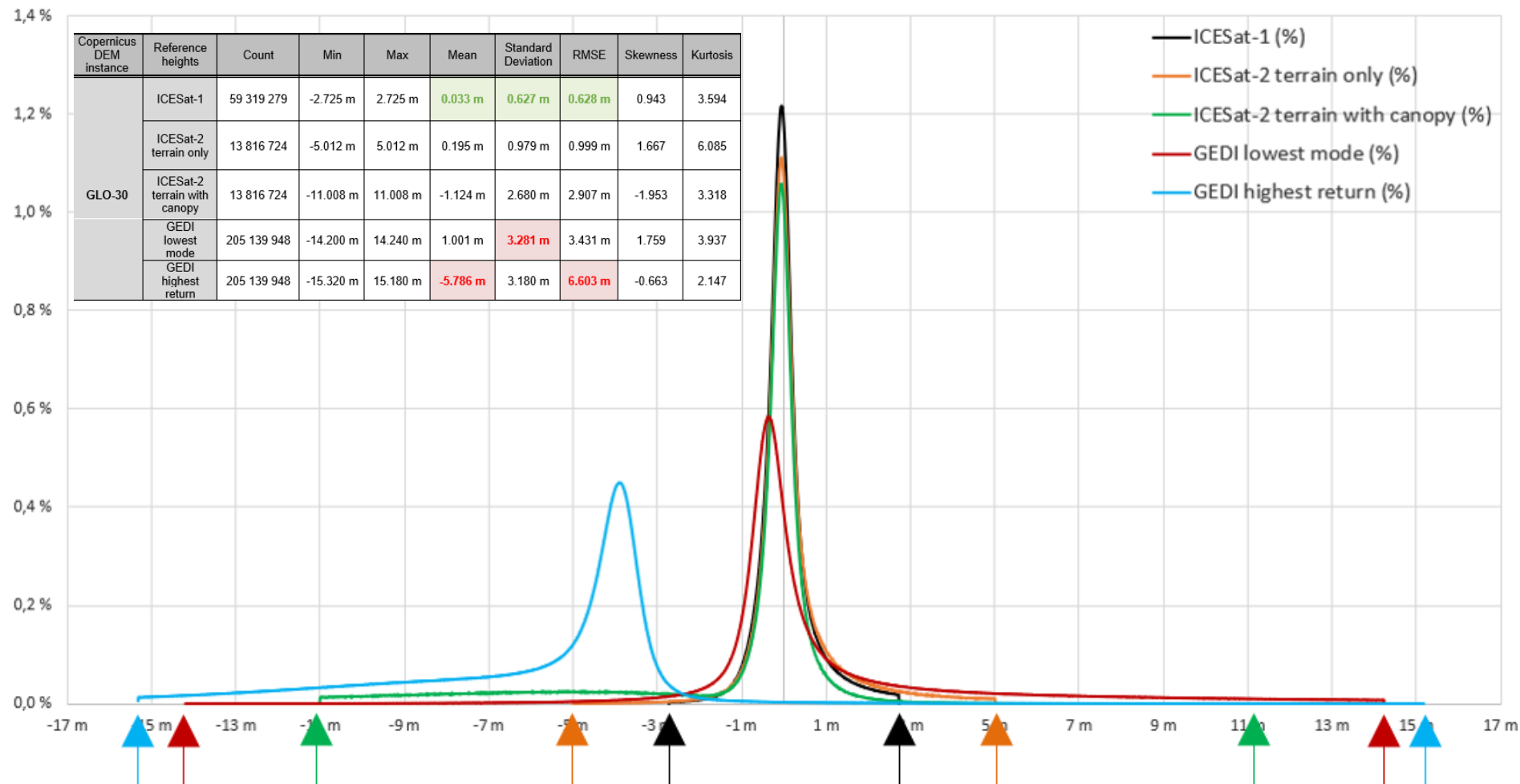




Study 2 - Height errors depending on LiDAR mission / mode

GLO-30

Copernicus DEM GLO-30 - Comparison with ICESat-1, ICESat-2 and GEDI (LE95)

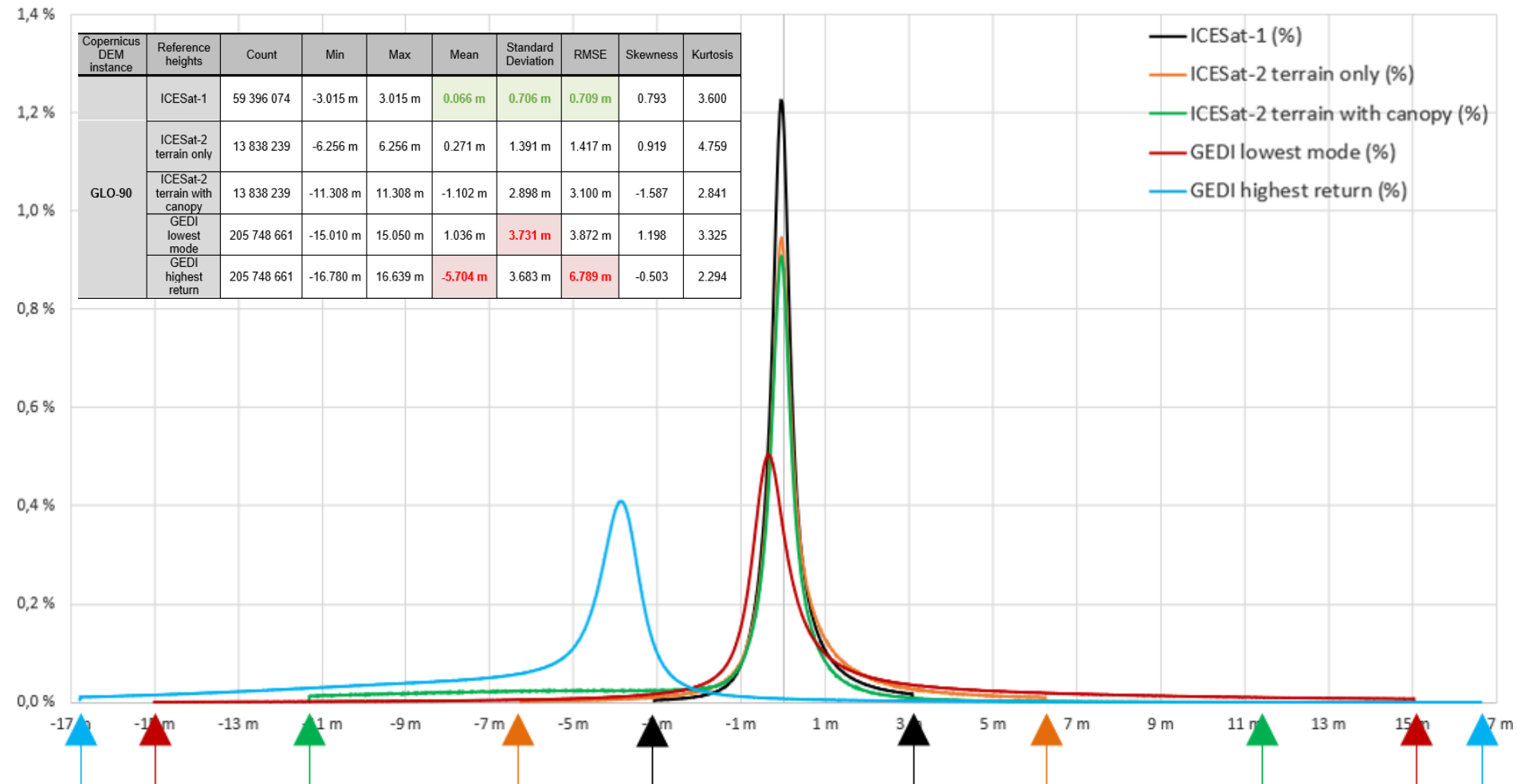




Study 2 - Height errors depending on LiDAR mission / mode

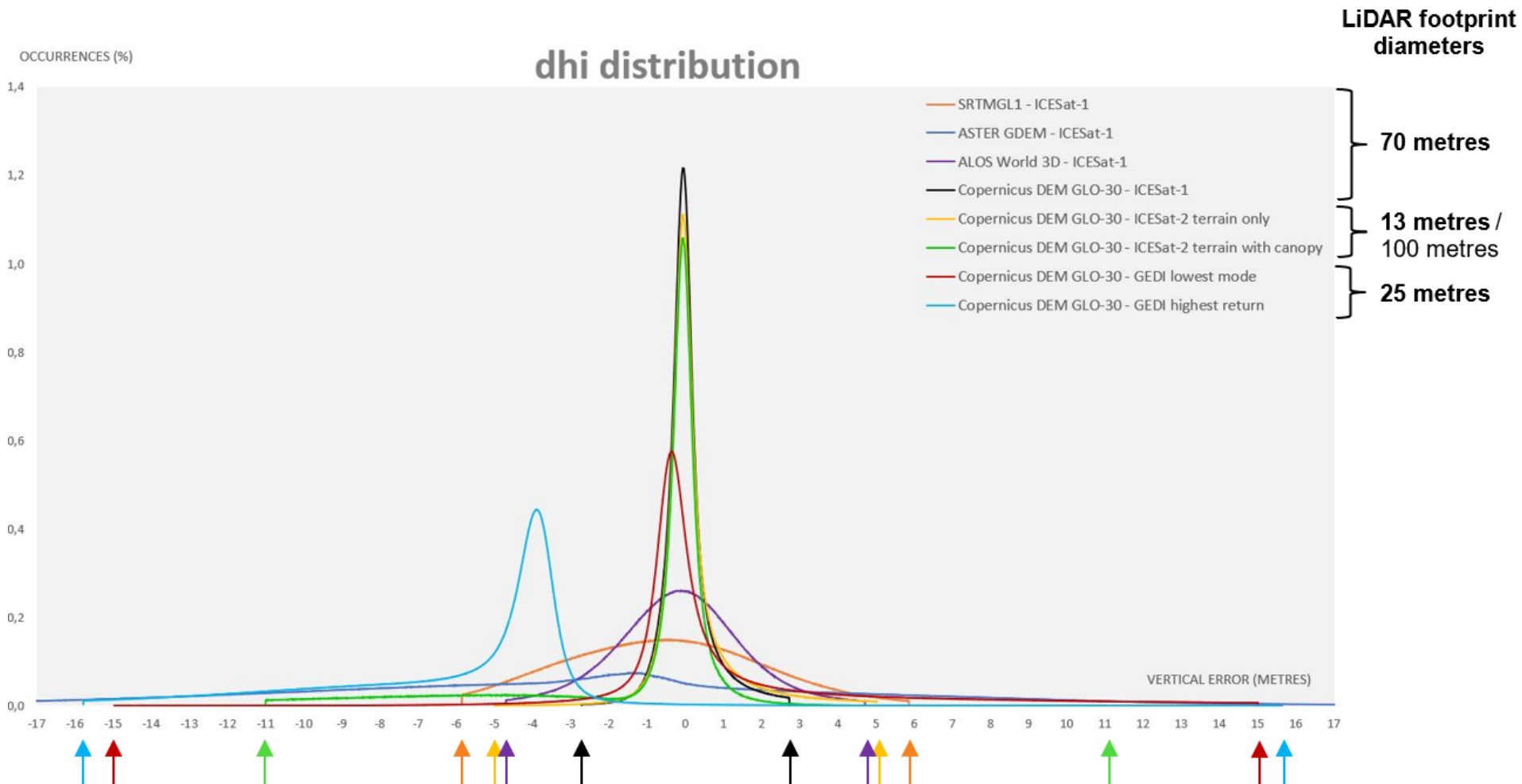
GLO-90

Copernicus DEM GLO-90 - Comparison with ICESat-1, ICESat-2 and GEDI (LE95)



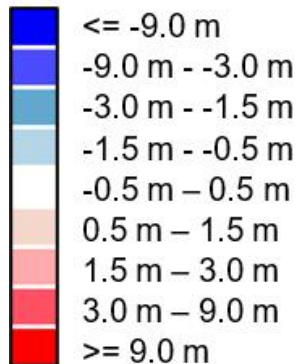
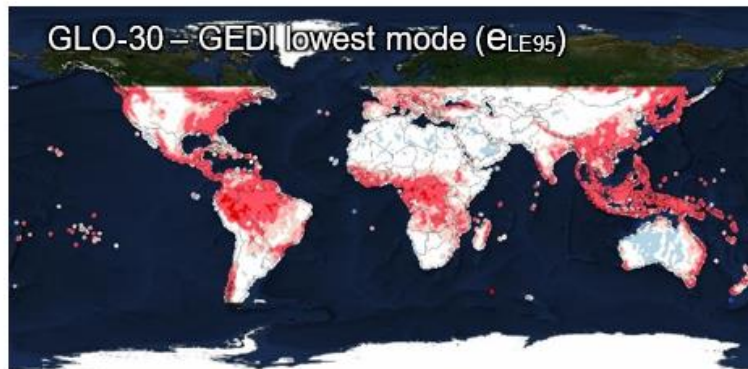
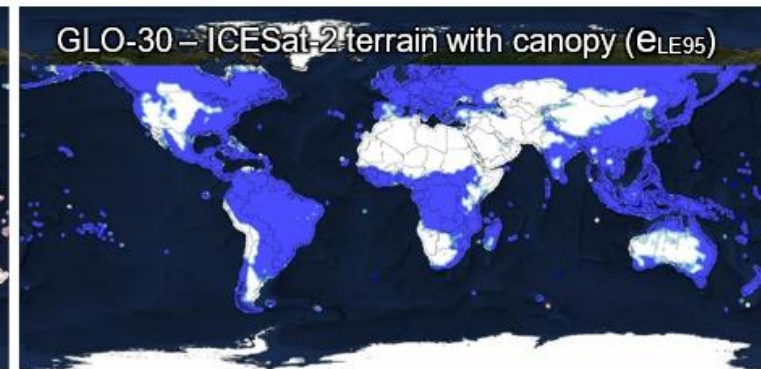
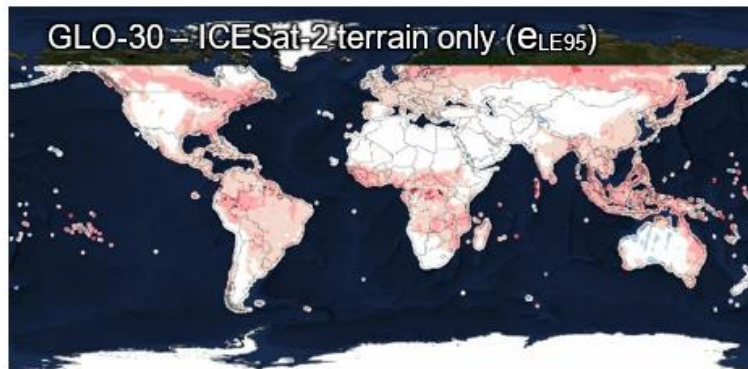
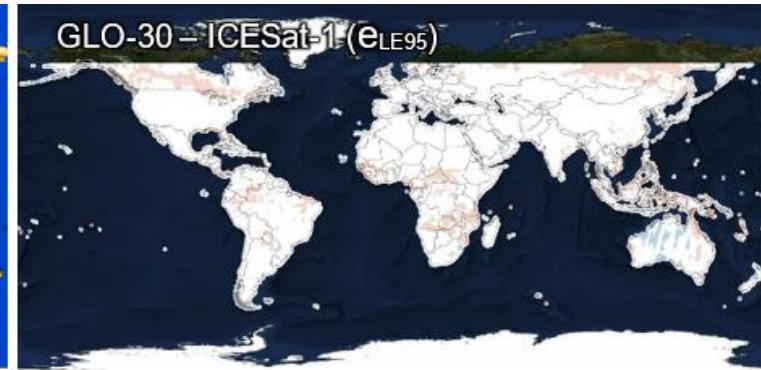
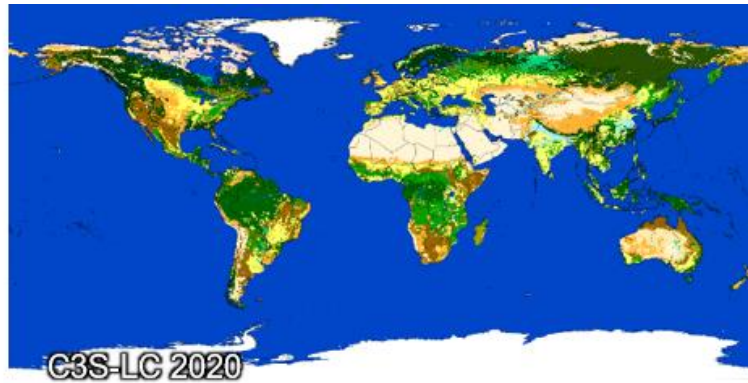


Study 2 - Comparison of COP-DEM GLO-30 with the other DEMs



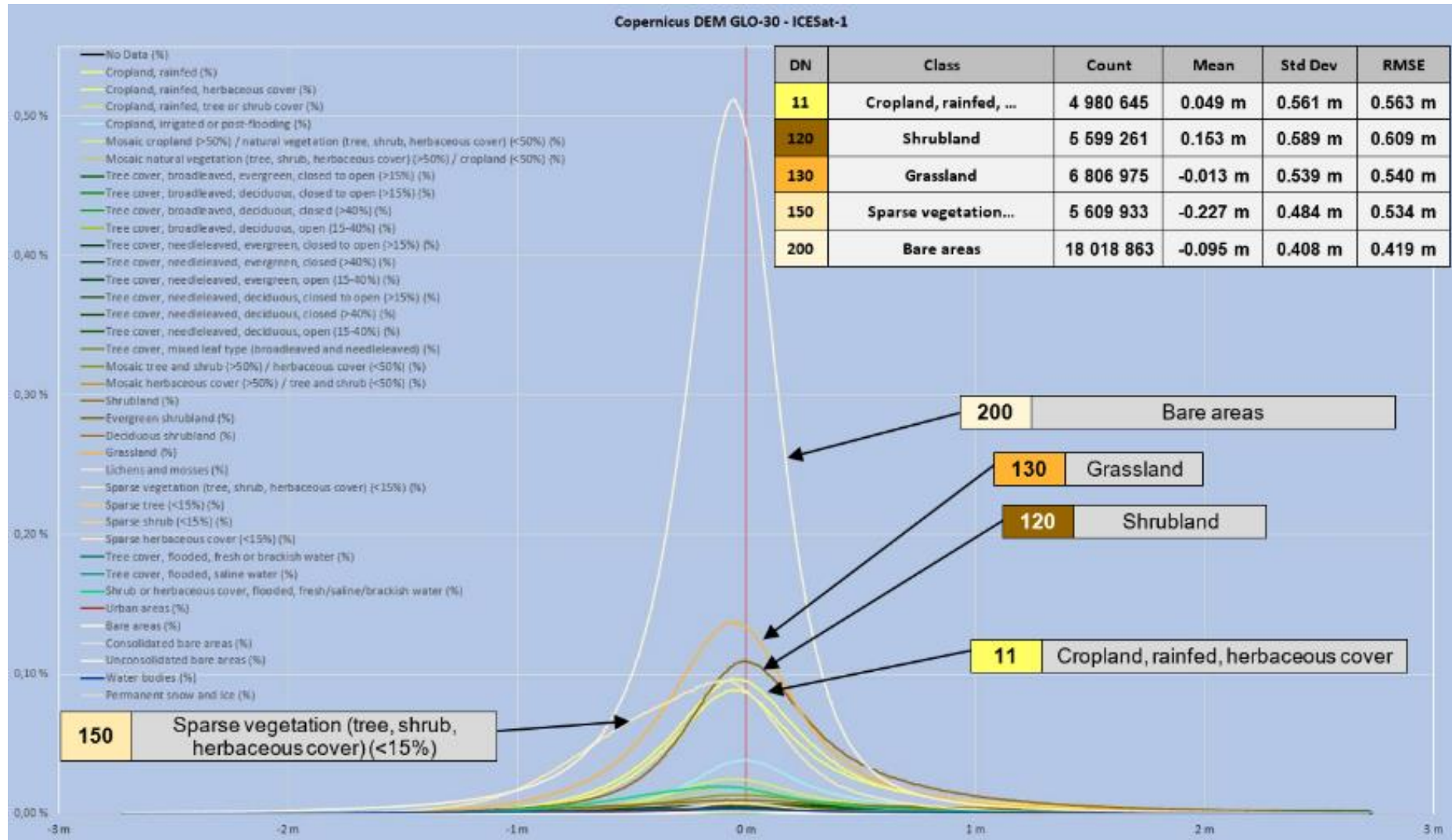


Study 2 - Spatial distribution of COP-DEM GLO-30 errors (LE95)





Study 2 - Influence of LULC (C3S-LC) on height errors





Study 2 - COP-DEM is above the terrain

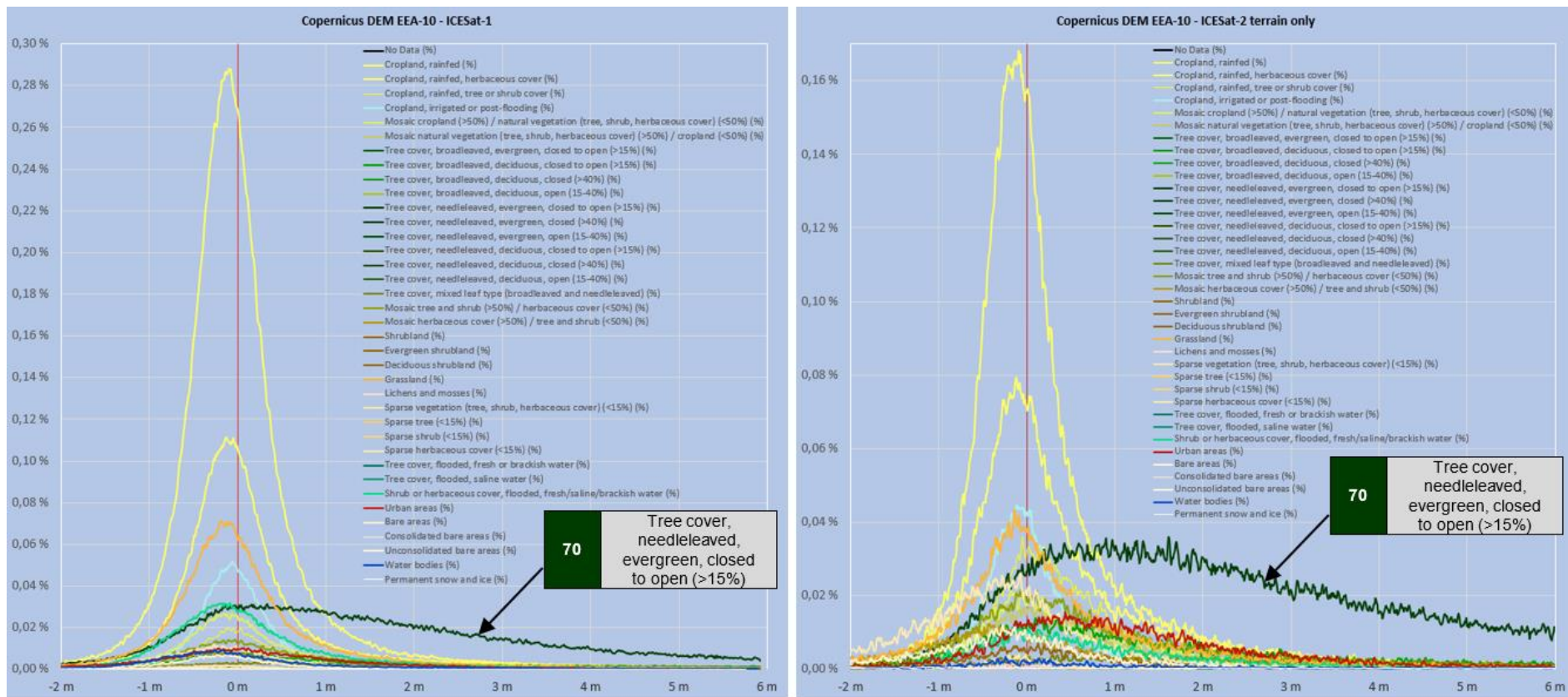


Figure 152– Comparison of errors histograms (Copernicus DEM EEA-10 – ICESat-1 LE95) on the left and (Copernicus DEM EEA-10 – ICESat-2 terrain only LE95) on the right - classified with C3S-LC 2013.



Study 2 - But COP-DEM is also below the surface !

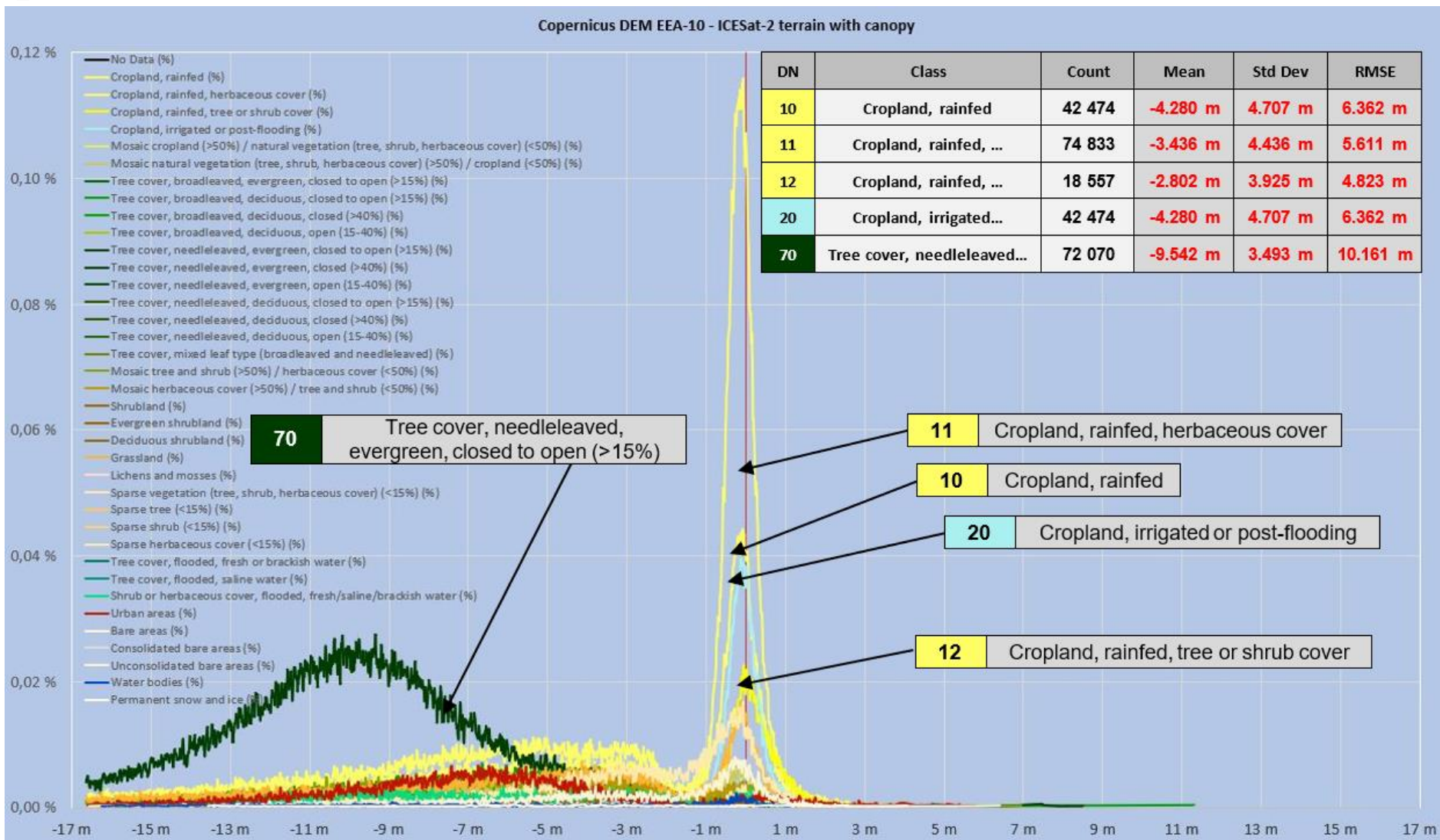


Figure 153 – Error histograms of (Copernicus DEM EEA-10 – ICESat-2 terrain with canopy LE95) classified with C3S-LC 2013.



Merci de votre attention
Thank you for your attention

Questions ?



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